

CHAPTER-6

***g* η -HOMEOMORPHISM IN TOPOLOGICAL SPACES AND TOPOLOGICAL ORDERED SPACES**

6.1. INTRODUCTION

In 1973, Noiri [78] introduced the concept of generalized closed maps in topological spaces. In 1991 Maki et al. [65] introduced g -homeomorphisms and studied their properties. In 2002, Veera Kumar [111] introduced homeomorphism in topological ordered spaces. Many authors like [27, 30, 57, 67, 72, 76, 82, 92, 106] contributed much to develop the concept of homeomorphism in topological spaces.

In this chapter, a new class of $g\eta$ -closed maps, $g\eta$ -open maps and $g\eta$ -homeomorphism in topological spaces and topological ordered spaces are introduced. Also the association of these maps with other existing maps and their properties are studied.

6.2. $g\eta$ -CLOSED MAPS

The notion of $g\eta$ -closed maps are studied in this section.

Definition 6.2.1: A map $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ is said to be a $g\eta$ -closed map if the image of every closed set in (X, τ) is $g\eta$ -closed in (Y, σ) .

Example 6.2.2: Let $X = Y = \{e, f, g, h\}$, $\tau = \{X, \varphi, \{g\}, \{e, f\}, \{e, f, g\}\}$ and $\sigma = \{Y, \varphi, \{f\}, \{g, h\}, \{f, g, h\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = e$, $\mathfrak{a}(f) = f$, $\mathfrak{a}(g) = h$, $\mathfrak{a}(h) = g$. Then $\mathfrak{a}(\{h\}) = \{g\}$, $\mathfrak{a}(\{g, h\}) = \{g, h\}$, $\mathfrak{a}(\{e, f, h\}) = \{e, f, g\}$. Therefore \mathfrak{a} is $g\eta$ -closed map. Since the image of every closed set in X is $g\eta$ -closed in Y .

Theorem 6.2.3: Let (X, τ) and (Y, σ) be any two topological spaces. Then for a mapping $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$. The following results are true.

(i) Every closed map is $g\eta$ -closed map.

- (ii) Every α -closed map is $g\eta$ -closed map.
- (iii) Every r -closed map is $g\eta$ -closed map.
- (iv) Every η -closed map is $g\eta$ -closed map.
- (v) Every g -closed map is $g\eta$ -closed map.
- (vi) Every g^* -closed map is $g\eta$ -closed map.
- (vii) Every αg -closed map is $g\eta$ -closed map.
- (viii) Every $g\alpha$ -closed map is $g\eta$ -closed map.

Proof: (i) Let $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ be a closed map and W be a closed set in X , then $\mathfrak{a}(W)$ is closed in Y and hence $g\eta$ -closed in Y . Thus \mathfrak{a} is $g\eta$ -closed.

Proof of (ii) to (viii) are similar to (i).

Remark 6.2.4: The following example reveals that the converse of the above theorem need not be true.

Example 6.2.5: (i) Let $X = Y = \{e, f, g, h\}$, $\tau = \{X, \varphi, \{e\}, \{f\}, \{e, f\}, \{e, f, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f, h\}, \{e, f, h\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = e$, $\mathfrak{a}(f) = f$, $\mathfrak{a}(g) = g$, $\mathfrak{a}(h) = h$. Then the function is $g\eta$ -closed but not closed, r -closed, α -closed, g -closed, g^* -closed, αg -closed, $g\alpha$ -closed as the image of closed set $\{h\}$ in X is $\{h\}$ which is $g\eta$ -closed but not closed, r -closed, α -closed, g -closed, g^* -closed, αg -closed, $g\alpha$ -closed in Y .

(ii) Let $X = Y = \{e, f, g, h\}$, $\tau = \{X, \varphi, \{e\}, \{f\}, \{e, f\}, \{e, f, g\}\}$ and $\sigma = \{Y, \varphi, \{f\}, \{g, h\}, \{f, g, h\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = e$, $\mathfrak{a}(f) = g$, $\mathfrak{a}(g) = f$, $\mathfrak{a}(h) = h$. Then the function is $g\eta$ -closed but not η -closed as the image of closed set $\{e, g, h\}$ in X is $\{e, f, h\}$ which is not η -closed in Y .

Remark 6.2.6: rg -closed map, gpr -closed map, gar -closed map and $g\eta$ -closed map are not dependent on each other.

Example 6.2.7: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{g\}, \{e, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f\}, \{e, f\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = f, \mathfrak{a}(f) = e, \mathfrak{a}(g) = g$. Here \mathfrak{a} is $g\eta$ -closed map. But \mathfrak{a} is not rg -closed map, gpr -closed map, gar -closed map. Since for closed set $\{f\}$ in X , $\mathfrak{a}(\{f\}) = \{e\}$ is $g\eta$ -closed but not rg -closed, gpr -closed, gar -closed in Y .

Example 6.2.8: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{g\}, \{e, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = g, \mathfrak{a}(f) = e, \mathfrak{a}(g) = f$. Here \mathfrak{a} is rg -closed map, gpr -closed map, gar -closed map. But \mathfrak{a} is not $g\eta$ -closed map. Since for closed set $\{e, f\}$ in X , $\mathfrak{a}(\{e, f\}) = \{e, g\}$ is rg -closed, gpr -closed, gar -closed but not $g\eta$ -closed in Y .

Remark 6.2.9: The composition of two $g\eta$ -closed maps need not be a $g\eta$ -closed map as seen from the following example.

Example 6.2.10: Let $X = Y = Z = \{e, f, g, h\}$, $\tau = \{X, \varphi, \{g\}, \{e, f\}, \{e, f, g\}\}$, $\sigma = \{Y, \varphi, \{f\}, \{g, h\}, \{f, g, h\}\}$ and $\mu = \{Z, \varphi, \{e\}, \{f\}, \{e, f\}, \{e, f, g\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $\mathfrak{a}(e) = f, \mathfrak{a}(f) = e, \mathfrak{a}(g) = h, \mathfrak{a}(h) = g$ and $\mathfrak{b}: (Y, \sigma) \rightarrow (Z, \mu)$ be defined as $\mathfrak{b}(e) = f, \mathfrak{b}(f) = g, \mathfrak{b}(g) = e, \mathfrak{b}(h) = h$. Then the function \mathfrak{a} and \mathfrak{b} are $g\eta$ -closed map but their composition $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is not $g\eta$ -closed map, since for the closed set $\{e, f, h\}$ in (X, τ) , $(\mathfrak{b} \circ \mathfrak{a})(\{e, f, h\}) = \{e, f, g\}$ is not $g\eta$ -closed in (Z, μ) .

Theorem 6.2.11: Let $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ and $\mathfrak{b}: (Y, \sigma) \rightarrow (Z, \mu)$ be functions. Then the following properties hold:

- (i) If \mathfrak{a} is closed map and \mathfrak{b} is $g\eta$ -closed then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is $g\eta$ -closed.
- (ii) If \mathfrak{a} is continuous and surjective, \mathfrak{b} is $g\eta$ -closed then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is $g\eta$ -closed map.
- (iii) If \mathfrak{a} is $g\eta$ -closed and \mathfrak{b} is $g\eta$ -irresolute, injective then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is $g\eta$ -closed map.

(iv) If \mathfrak{a} is $g\eta$ -closed map and \mathfrak{b} is $g\eta$ -continuous then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is continuous.

(v) If \mathfrak{a} is η -closed map and \mathfrak{b} is $g\eta$ -continuous then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is η -continuous.

(vi) If \mathfrak{a} is η -closed map and \mathfrak{b} is $g\eta$ -continuous then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is η -irresolute.

(vii) If \mathfrak{a} is η -closed map and \mathfrak{b} is $g\eta$ -continuous then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is continuous.

(viii) If \mathfrak{a} is irresolute and η -closed map and \mathfrak{b} is $g\eta$ -continuous then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is $g\eta$ -continuous.

(ix) If \mathfrak{a} is $g\eta$ -closed map and \mathfrak{b} is contra $g\eta$ -continuous then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is contra continuous.

(x) If \mathfrak{a} is η -closed map and \mathfrak{b} is contra $g\eta$ -continuous then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is contra η -continuous.

(xi) If \mathfrak{a} is η -closed map and \mathfrak{b} is contra $g\eta$ -ccontinuous then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is contra continuous.

(xii) If \mathfrak{a} is η -closed map and \mathfrak{b} is contra $g\eta$ -continuous then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is contra $g\eta$ -ccontinuous.

Proof: (i) Let R be a closed set in X . Then $\mathfrak{a}(R)$ is a closed set in Y . Hence $\mathfrak{b}(\mathfrak{a}(R)) = (\mathfrak{b} \circ \mathfrak{a})(R)$ is a $g\eta$ -closed set in Z . Therefore $\mathfrak{b} \circ \mathfrak{a}$ is a $g\eta$ -closed map.

(ii) Let R be a closed set in Y . Since \mathfrak{a} is continuous, $\mathfrak{a}^{-1}(R)$ is closed in X and since $\mathfrak{b} \circ \mathfrak{a}$ is $g\eta$ -closed, $\mathfrak{b} \circ \mathfrak{a}(R) = \mathfrak{b}(\mathfrak{a}(R))$ is $g\eta$ -closed in Z . Therefore, $\mathfrak{b} \circ \mathfrak{a}$ is a $g\eta$ -closed map.

(iii) Let R be a $g\eta$ -closed set in Z . Since \mathbb{b} is $g\eta$ -irresolute, $\mathbb{b}^{-1}(R)$ is $g\eta$ -closed set in Y . Since \mathbb{a} is $g\eta$ -closed, $(\mathbb{b} \circ \mathbb{a})(R) = \mathbb{b}(\mathbb{a}(R))$ is $g\eta$ -closed in Z . Hence $(\mathbb{b} \circ \mathbb{a})$ is $g\eta$ -closed.

(iv) Let R be a closed set in Z , since \mathbb{b} is a $g\eta$ -continuous, $\mathbb{b}^{-1}(R)$ is $g\eta$ -closed set in Y . Since \mathbb{a} is $g\eta$ -closed map, $\mathbb{a}^{-1}(\mathbb{b}^{-1}(R)) = (\mathbb{b} \circ \mathbb{a})^{-1}(R)$ is closed in X . Hence $\mathbb{b} \circ \mathbb{a}$ is continuous.

(v) Let R be a closed set in Z , since \mathbb{b} is a $g\eta$ -continuous, $\mathbb{b}^{-1}(R)$ is η -closed set which is also $g\eta$ -closed set in Y . Since \mathbb{a} is η -closed map, $\mathbb{a}^{-1}(\mathbb{b}^{-1}(R)) = (\mathbb{b} \circ \mathbb{a})^{-1}(R)$ is η -closed in X . Hence $\mathbb{b} \circ \mathbb{a}$ is η -continuous.

(vi) Let R be a closed set in Z , which is η -closed in Z . since \mathbb{b} is a $g\eta$ -continuous function, $\mathbb{b}^{-1}(R)$ is η -closed which is also $g\eta$ -closed in Y . Since \mathbb{a} is η -closed, $\mathbb{a}^{-1}(\mathbb{b}^{-1}(R)) = (\mathbb{b} \circ \mathbb{a})^{-1}(R)$ is η -closed in X . Hence $\mathbb{b} \circ \mathbb{a}$ is η -irresolute.

(vii) Let R be a closed set in Z , since \mathbb{b} is a $g\eta$ -continuous function, $\mathbb{b}^{-1}(R)$ is η -closed set which is also $g\eta$ -closed in Y . Since \mathbb{a} is η -closed map, $\mathbb{a}^{-1}(\mathbb{b}^{-1}(R)) = (\mathbb{b} \circ \mathbb{a})^{-1}(R)$ is closed in X . Hence $\mathbb{b} \circ \mathbb{a}$ is continuous.

(viii) Let R be a closed set in Z , since \mathbb{b} is a $g\eta$ -continuous function, $\mathbb{b}^{-1}(R)$ is η -closed set which is also $g\eta$ -closed in Y . Since \mathbb{a} is irresolute and η -closed map, $\mathbb{a}^{-1}(\mathbb{b}^{-1}(R)) = (\mathbb{b} \circ \mathbb{a})^{-1}(R)$ is $g\eta$ -closed in X and every closed set is $g\eta$ -closed. Hence $\mathbb{b} \circ \mathbb{a}$ is $g\eta$ -continuous.

(ix) Let R be an open set in Z , since \mathbb{b} is a contra $g\eta$ -continuous function, $\mathbb{b}^{-1}(R)$ is $g\eta$ -closed in Y . Since \mathbb{a} is $g\eta$ -closed map, $\mathbb{a}^{-1}(\mathbb{b}^{-1}(R)) = (\mathbb{b} \circ \mathbb{a})^{-1}(R)$ is closed in X . Hence $\mathbb{b} \circ \mathbb{a}$ is contra continuous.

(x) Let R be an open set in Z , since \mathbb{b} is a contra $g\eta$ -continuous function, $\mathbb{b}^{-1}(R)$ is η -closed in Y . As every η -closed set is $g\eta$ -closed. Since \mathbb{a} is η -closed map, $\mathbb{a}^{-1}(\mathbb{b}^{-1}(R)) = (\mathbb{b} \circ \mathbb{a})^{-1}(R)$ is closed which is η -closed in X . Hence $\mathbb{b} \circ \mathbb{a}$ is contra η -continuous.

(xi) Let R be an open set in Z , since \mathbb{b} is a contra $g\eta$ -continuous function, $\mathbb{b}^{-1}(R)$ is η -closed which is also $g\eta$ -closed in Y . Since \mathfrak{a} is an η -closed map, $\mathfrak{a}^{-1}(\mathbb{b}^{-1}(R)) = (\mathbb{b} \circ \mathfrak{a})^{-1}(R)$ is closed in X . Hence $\mathbb{b} \circ \mathfrak{a}$ is contra continuous.

(xii) Let R be an open set in Z , since \mathbb{b} is a contra $g\eta$ -continuous function, $\mathbb{b}^{-1}(R)$ is η -closed which is also $g\eta$ -closed in Y . Since \mathfrak{a} is η -closed map, $\mathfrak{a}^{-1}(\mathbb{b}^{-1}(R)) = (\mathbb{b} \circ \mathfrak{a})^{-1}(R)$ is $g\eta$ -closed in X . As every closed set is $g\eta$ -closed. Hence $\mathbb{b} \circ \mathfrak{a}$ is contra $g\eta$ -continuous.

Theorem 6.2.12: Let (X, τ) , (Y, σ) be any two topological spaces, then if:

(i) $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ is $g\eta$ -closed and R is a closed subset of (X, τ) then $\mathfrak{a}_R: (R, \tau_R) \rightarrow (Y, \sigma)$ is $g\eta$ -closed.

(ii) $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ is $g\eta$ -closed and $R = \mathfrak{a}^{-1}(S)$, for some closed set S of (Y, σ) , then $\mathfrak{a}_R: (R, \tau_R) \rightarrow (Y, \sigma)$ is $g\eta$ -closed.

Proof: (i). Let S be a closed set of (R, τ_R) . Then $S = R \cap F$ for some closed set F of (X, τ) and so S is closed in (X, τ) . Since \mathfrak{a} is $g\eta$ -closed, then $\mathfrak{a}(S)$ is $g\eta$ -closed in (Y, σ) . But $\mathfrak{a}(S) = \mathfrak{a}_R(S)$. So \mathfrak{a}_R is $g\eta$ -closed in Y . Therefore \mathfrak{a}_R is a $g\eta$ -closed map.

(ii). Let F be a closed set of (R, τ_R) . Then $F = R \cap H$ for some closed set H of (X, τ) . Now $\mathfrak{a}_R(F) = \mathfrak{a}(F) = \mathfrak{a}(R \cap H) = \mathfrak{a}(\mathfrak{a}^{-1}(S) \cap H) = S \cap \mathfrak{a}(H)$. Since \mathfrak{a} is $g\eta$ -closed, then $\mathfrak{a}(H)$ is $g\eta$ -closed in (Y, σ) and so $S \cap \mathfrak{a}(H)$ is $g\eta$ -closed in (Y, σ) . Therefore \mathfrak{a}_R is a $g\eta$ -closed map.

Theorem 6.2.13: The map $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ is $g\eta$ -closed if and only if for each subset P of (Y, σ) and for each open set Q in (X, τ) containing $\mathfrak{a}^{-1}(P)$ there is a $g\eta$ -open set T of (Y, σ) contains P such that $P \subseteq T$ and $\mathfrak{a}^{-1}(T) \subseteq Q$.

Proof: Suppose \mathfrak{a} is $g\eta$ -closed. Let $P \subseteq Y$ and Q be an open set of (X, τ) such that $\mathfrak{a}^{-1}(P) \subseteq Q$. Now $X - Q$ is a closed set in (X, τ) . Since \mathfrak{a} is $g\eta$ -closed, $\mathfrak{a}(X - Q)$ is a $g\eta$ -closed set in (Y, σ) . Then $T = Y - \mathfrak{a}(X - Q)$ is a $g\eta$ -open set in (Y, σ) . $\mathfrak{a}^{-1}(P) \subseteq$

Q implies $P \subseteq T$ and $\mathfrak{a}^{-1}(T) = X - \mathfrak{a}^{-1}(\mathfrak{a}(X - Q)) \subseteq X - (X - Q) = Q$, That is $\mathfrak{a}^{-1}(T) \subseteq Q$.

Conversely, let F be a closed set of (X, τ) . Then $\mathfrak{a}^{-1}(\mathfrak{a}(X - F)) \subseteq (X - F)$ is an open set in (X, τ) . By hypothesis, there exists a $g\eta$ -open set T in (Y, σ) such that $\mathfrak{a}(X - F) \subseteq T$ and $\mathfrak{a}^{-1}(T) \subseteq (X - F)$ and so $F \subseteq Y - \mathfrak{a}^{-1}(T)$. Hence $(Y - T) \subseteq \mathfrak{a}(F) \subseteq \mathfrak{a}(\mathfrak{a}^{-1}(Y - T)) \subseteq (Y - T)$ which implies $\mathfrak{a}(F) \subseteq (X - F)$. Since $(Y - T)$ is $g\eta$ -closed, $\mathfrak{a}(F)$ is $g\eta$ -closed. That is $\mathfrak{a}(F)$ is $g\eta$ -closed in (Y, σ) . Therefore \mathfrak{a} is $g\eta$ -closed map.

6.3. $g\eta$ -OPEN MAPS

The notion of $g\eta$ -open maps are studied in this section.

Definition 6.3.1: A map $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ is said to be a $g\eta$ -open map if the image of every open set in (X, τ) is $g\eta$ -open in (Y, σ) .

Example 6.3.2: Let $X = Y = \{e, f, g, h\}$, $\tau = \{X, \varphi, \{f\}, \{g, h\}, \{f, g, h\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f\}, \{e, f\}, \{e, f, g\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = e, \mathfrak{a}(f) = g, \mathfrak{a}(g) = f, \mathfrak{a}(h) = h$. Then $\mathfrak{a}(\{f\}) = \{g\}, \mathfrak{a}(\{g, h\}) = \{f, h\}, \mathfrak{a}(\{f, g, h\}) = \{f, g, h\}$. Therefore \mathfrak{a} is $g\eta$ -open map. Since the image of every open set in X is $g\eta$ -open in Y .

Theorem 6.3.3: Let (X, τ) and (Y, σ) be a topological spaces. Then for a mapping $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$. The following results are true.

- (i) Every open map is $g\eta$ -open map.
- (ii) Every α -open map is $g\eta$ -open map.
- (iii) Every r -open map is $g\eta$ -open map.
- (iv) Every η -open map is $g\eta$ -open map.
- (v) Every g -open map is $g\eta$ -open map.
- (vi) Every g^* -open map is $g\eta$ -open map.

(vii) Every αg -open map is $g\eta$ -open map.

(viii) Every $g\alpha$ -open map is $g\eta$ -open map.

Proof: (i). Let $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ be an open map and G be an open set in X , then $\mathfrak{a}(G)$ is open in Y and hence $g\eta$ -open in Y . Thus \mathfrak{a} is $g\eta$ -open.

Proof of (ii) to (viii) are similar to (i).

Remark 6.3.4: The following example reveals that the converse of the above theorem need not be true.

Example 6.3.5: (i) Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{f\}, \{e, f\}\}$ and $\sigma = \{Y, \varphi, \{e\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$. Then the function is $g\eta$ -open but not η -open as the image of open set $\{e\}$ in X is $\{f\}$ which is $g\eta$ -open but not η -open in Y .

(ii) Let $X = Y = \{e, f, g, h\}$, $\tau = \{X, \varphi, \{f\}, \{g, h\}, \{f, g, h\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f\}, \{e, f\}, \{e, f, g\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = e$, $\mathfrak{a}(f) = g$, $\mathfrak{a}(g) = f$, $\mathfrak{a}(h) = h$. Then the function is $g\eta$ -open but not open, α -open, r -open, g -open, g^* -open, $g\alpha$ -open, αg -open. Since the image of open set $\{f, g, h\}$ in X is $\{f, g, h\}$ which is $g\eta$ -open but not open, α -open, r -open, g -open, g^* -open, $g\alpha$ -open, αg -open in Y .

Remark 6.3.6: rg -open map, gpr -open map, gar -open map and $g\eta$ -open map are not dependent on each other.

Example 6.3.7: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{f, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{g\}, \{e, g\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = e$, $\mathfrak{a}(f) = f$, $\mathfrak{a}(g) = g$. Here \mathfrak{a} is $g\eta$ -open map. But \mathfrak{a} is not rg -open map, gpr -open map, gar -open map. Since for open set $\{f, g\}$ in X , $\mathfrak{a}(\{f, g\}) = \{f, g\}$ is $g\eta$ -open but not rg -open, gpr -open, gar -open in Y .

Example 6.3.8: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{g\}, \{e, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$. Here \mathfrak{a} is rg -open map, gpr -open map, gar -open map. But \mathfrak{a} is not $g\eta$ -open map. Since for open set $\{e, g\}$ in X , $\mathfrak{a}(\{e, g\}) = \{f, g\}$ is rg -open, gpr -open, gar -open but not $g\eta$ -open in Y .

Remark 6.3.9: The composition of two $g\eta$ -open maps need not be a $g\eta$ -open map as seen from the following example.

Example 6.3.10: Let $X = Y = Z = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{g\}, \{e, g\}\}$, $\sigma = \{Y, \varphi, \{f, g\}\}$ and $\mu = \{Z, \varphi, \{e\}, \{f\}, \{e, f\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$ and $\mathfrak{b}: (Y, \sigma) \rightarrow (Z, \mu)$ be defined as $\mathfrak{b}(e) = f$, $\mathfrak{b}(f) = g$, $\mathfrak{b}(g) = e$. Then the function \mathfrak{a} and \mathfrak{b} are $g\eta$ -open maps but their composition $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is not a $g\eta$ -open map, since for the open set $\{e\}$ in (X, τ) , $(\mathfrak{b} \circ \mathfrak{a})(\{e\}) = \{g\}$ is not $g\eta$ -open in (Z, μ) .

Theorem 6.3.11: For any bijection $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$, the following statements are equivalent.

- (i) $\mathfrak{a}^{-1}: (Y, \sigma) \rightarrow (X, \tau)$ is $g\eta$ -continuous.
- (ii) \mathfrak{a} is a $g\eta$ -open map.
- (iii) \mathfrak{a} is a $g\eta$ -closed map.

Proof: (i) \Rightarrow (ii) Let Q be any open set of (X, τ) . By assumption, $(\mathfrak{a}^{-1})^{-1}(Q) = \mathfrak{a}(Q)$ is $g\eta$ -open in (Y, σ) and so \mathfrak{a} is $g\eta$ -open map.

(ii) \Rightarrow (iii) Let G be a closed set of (X, τ) . Then $X - G$ is open in (X, τ) . By assumption, $\mathfrak{a}(X - G) = X - \mathfrak{a}(G)$ is $g\eta$ -open in (Y, σ) and therefore $\mathfrak{a}(G)$ is $g\eta$ -closed in (Y, σ) . Hence \mathfrak{a} is a $g\eta$ -closed map.

(iii) \Rightarrow (i) Let G be a closed set of (X, τ) . By assumption, $\mathfrak{a}(G)$ is $g\eta$ -closed in (Y, σ) . But $\mathfrak{a}(G) = (\mathfrak{a}^{-1})^{-1}(G)$ and therefore \mathfrak{a}^{-1} is $g\eta$ -continuous on (Y, σ) .

Theorem 6.3.12: Let (X, τ) and (Y, σ) be any mapping. If \mathfrak{a} is a $g\eta$ -open mapping, then for each $x \in X$ and for each neighbourhood A of x in (X, τ) , there exists a $g\eta$ -neighbourhood B of $\mathfrak{a}(x)$ in (Y, σ) such that $B \subseteq \mathfrak{a}(A)$.

Proof: Let $x \in X$ and A be an arbitrary neighbourhood of x . Then there exists an open set G in (X, τ) such that $x \in G \subseteq A$. By assumption, $\mathfrak{a}(G)$ is a $g\eta$ -open set in (Y, σ) . Further, $\mathfrak{a}(x) \in \mathfrak{a}(G) \subseteq \mathfrak{a}(A)$, clearly $\mathfrak{a}(A)$ is a $g\eta$ -neighbourhood of $\mathfrak{a}(x)$ in (Y, σ) and so the theorem holds, by taking $B = \mathfrak{a}(G)$.

Theorem 6.3.13: Let X, Y and Z be topological spaces.

(i) If $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ is an open map and $\mathfrak{b}: (Y, \sigma) \rightarrow (Z, \mu)$ is a $g\eta$ -open map, then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is a $g\eta$ -open map.

(ii) If $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ and $\mathfrak{b}: (Y, \sigma) \rightarrow (Z, \mu)$ are open maps then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is a $g\eta$ -open map.

(iii) If $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ is an open map and $\mathfrak{b}: (Y, \sigma) \rightarrow (Z, \mu)$ is an η -open map, then $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is a $g\eta$ -open map.

Proof: (i) Let Q be an open set in X . Since \mathfrak{a} is an open map, $\mathfrak{a}(Q)$ is open in Y . Then $\mathfrak{b}(\mathfrak{a}(Q)) = (\mathfrak{b} \circ \mathfrak{a})(Q)$ is a $g\eta$ -open set in Z . Therefore, $\mathfrak{b} \circ \mathfrak{a}$ is a $g\eta$ -open map.

(ii) Let Q be an open set in X . Since \mathfrak{a} is an open map, $\mathfrak{a}(Q)$ is open in Y . Also, since \mathfrak{b} is an open map, $\mathfrak{b}(\mathfrak{a}(Q))$ is open in Z . That is, $(\mathfrak{b} \circ \mathfrak{a})(Q)$ is an open set in Z . And every open set is $g\eta$ -open, $(\mathfrak{b} \circ \mathfrak{a})(Q)$ is a $g\eta$ -open set in Z . Therefore, $\mathfrak{b} \circ \mathfrak{a}$ is a $g\eta$ -open map.

(iii) Let Q be an open set in X . Since \mathfrak{a} is an open map, $\mathfrak{a}(Q)$ is open in Y . Then $\mathfrak{b}(\mathfrak{a}(Q))$ is an η -open in Z . That is, $(\mathfrak{b} \circ \mathfrak{a})(Q)$ is an η -open set in Z . As every η -open set is $g\eta$ -open, $(\mathfrak{b} \circ \mathfrak{a})(Q)$ is a $g\eta$ -open set in Z . Hence, $\mathfrak{b} \circ \mathfrak{a}$ is a $g\eta$ -open map.

Theorem 6.3.14: The map $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ is $g\eta$ -open if and only if for any subset P of (Y, σ) and any closed set F in (X, τ) containing $\mathfrak{a}^{-1}(P)$, there exists a $g\eta$ -closed set S of (Y, σ) containing P such that $\mathfrak{a}^{-1}(S) \subseteq F$.

Proof: Suppose \mathfrak{a} is $g\eta$ -open map. Let $P \subseteq Y$ and F be a closed set of (X, τ) such that $\mathfrak{a}^{-1}(P) \subseteq F$. Now $X - F$ is an open set in (X, τ) . Since \mathfrak{a} is $g\eta$ -open, $\mathfrak{a}(X - F)$ is a $g\eta$ -open set in (Y, σ) . Then $S = Y - \mathfrak{a}(X - F)$ is a $g\eta$ -closed set in (Y, σ) . $\mathfrak{a}^{-1}(P) \subseteq F$ implies $P \subseteq S$ and $\mathfrak{a}^{-1}(S) = X - \mathfrak{a}(\mathfrak{a}^{-1}(X - F)) \subseteq X - (X - F) = F$. That is $\mathfrak{a}^{-1}(S) \subseteq F$.

Conversely, let Q be an open set of (X, τ) . Then $\mathfrak{a}^{-1}(X - \mathfrak{a}(Q)) \subseteq X - Q$ and $X - Q$ is a closed set in (X, τ) . By hypothesis, there exists a $g\eta$ -closed set S in (Y, σ) such that $X - \mathfrak{a}(Q) \subseteq S$ and $\mathfrak{a}^{-1}(S) \subseteq X - Q$ and so $Q \subseteq X - \mathfrak{a}^{-1}(S)$. Hence $Y - S \subseteq \mathfrak{a}(Q) \subseteq \mathfrak{a}(Y - \mathfrak{a}^{-1}(S))$ which implies $\mathfrak{a}(Q) \subseteq Y - S$. Since $Y - S$ is $g\eta$ -open, $\mathfrak{a}(Q)$ is $g\eta$ -open in (Y, σ) and therefore \mathfrak{a} is $g\eta$ -open map.

6.4. $g\eta$ -HOMEOMORPHISM

Definition 6.4.1: A bijection $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ is called an η -homeomorphism if \mathfrak{a} is both η -continuous map and η -open map. That is, both \mathfrak{a} and \mathfrak{a}^{-1} are η -continuous map.

Definition 6.4.2: A bijection $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ is called a $g\eta$ -homeomorphism if \mathfrak{a} is both $g\eta$ -continuous map and $g\eta$ -open map. That is, both \mathfrak{a} and \mathfrak{a}^{-1} are $g\eta$ -continuous map.

Example 6.4.3: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{f, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{g\}, \{e, g\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = g$, $\mathfrak{a}(f) = f$, $\mathfrak{a}(g) = e$. Here the sets $\{f\}$, $\{e, f\}$, $\{f, g\}$ are closed in Y . Then $\mathfrak{a}^{-1}(\{f\}) = \{f\}$, $\mathfrak{a}^{-1}(\{e, f\}) = \{f, g\}$, $\mathfrak{a}^{-1}(\{f, g\}) = \{e, f\}$ are $g\eta$ -closed in X . Therefore \mathfrak{a} is $g\eta$ -continuous. And the sets $\{e\}$, $\{f, g\}$ are open in X . Then $\mathfrak{a}(e) = g$, $\mathfrak{a}(f, g) = \{e, f\}$ are $g\eta$ -open in Y . Therefore \mathfrak{a} is open map. Hence \mathfrak{a} is $g\eta$ -homeomorphism.

Theorem 6.4.4: Let (X, τ) and (Y, σ) be a topological spaces. Then for a mapping $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$. The following results are true.

- (i) Every homeomorphism is $g\eta$ -homeomorphism.
- (ii) Every α -homeomorphism is $g\eta$ -homeomorphism.
- (iii) Every r -homeomorphism is $g\eta$ -homeomorphism.
- (iv) Every η -homeomorphism is $g\eta$ -homeomorphism.
- (v) Every g -homeomorphism is $g\eta$ -homeomorphism.
- (vi) Every g^* -homeomorphism is $g\eta$ -homeomorphism.
- (vii) Every αg -homeomorphism is $g\eta$ -homeomorphism.
- (viii) Every $g\alpha$ -homeomorphism is $g\eta$ -homeomorphism.

Proof: (i) Let $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ be a homeomorphism. Then \mathfrak{a} and \mathfrak{a}^{-1} are continuous and \mathfrak{a} is bijection. Since every continuous function is $g\eta$ -continuous, \mathfrak{a} and \mathfrak{a}^{-1} are $g\eta$ -continuous. Hence \mathfrak{a} is $g\eta$ -homeomorphism.

Proof of (ii) to (viii) are similar to (i).

Remark 6.4.5: The following example reveals that the converse of the above theorem need not be true.

(i) Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}\}$ and $\sigma = \{Y, \varphi, \{f, g\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$. Then the function is $g\eta$ -homeomorphism. But $\mathfrak{a}^{-1}(\{e\}) = \{f\}$ is $g\eta$ -closed but not closed in X . Here the set $\{e\}$ is closed in Y . Therefore \mathfrak{a} is not $g\eta$ -continuous. Hence \mathfrak{a} is $g\eta$ -homeomorphism but not homeomorphism.

(ii) Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{g\}, \{e, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f\}, \{e, f\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = e$, $\mathfrak{a}(f) = f$, $\mathfrak{a}(g) = g$. Then the function is $g\eta$ -homeomorphism. But $\mathfrak{a}(\{e, g\}) = \{e, g\}$ is $g\eta$ -open but not r -open in Y . Here the

set $\{e, g\}$ is open in X . Therefore \mathfrak{a} is $g\eta$ -open map but not r -open map. Hence \mathfrak{a} is not r -homeomorphism.

(iii) Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{f, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{g\}, \{e, g\}\}$. Define $\mathfrak{a} : (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = g, \mathfrak{a}(f) = f, \mathfrak{a}(g) = e$. Then the function is $g\eta$ -homeomorphism. But $\mathfrak{a}(\{f, g\}) = \{e, f\}$ is $g\eta$ -open but not g -open, g^* -open, α -open, αg -open, $g\alpha$ -open in Y . Here the set $\{f, g\}$ is open in X . Therefore \mathfrak{a} is $g\eta$ -open map but not g -open, g^* -open, α -open, αg -open, $g\alpha$ -open map. Hence \mathfrak{a} is not g -homeomorphism, g^* -homeomorphism, α -homeomorphism, αg -homeomorphism, $g\alpha$ -homeomorphism.

(iv) Let $X = Y = \{e, f, g, h\}$, $\tau = \{X, \varphi, \{g\}, \{e, f\}, \{e, f, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f\}, \{e, f\}, \{e, f, g\}\}$. Define $\mathfrak{a} : (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = f, \mathfrak{a}(f) = e, \mathfrak{a}(g) = g, \mathfrak{a}(h) = h$. Then the function is $g\eta$ -homeomorphism. But $\mathfrak{a}(\{g\}) = \{g\}$ is $g\eta$ -open but not η -open in Y . Here the set $\{g\}$ is open in X . Therefore \mathfrak{a} is not η -homeomorphism.

Remark 6.4.6: rg -homeomorphism, gpr -homeomorphism, gar -homeomorphism and $g\eta$ -homeomorphism are not dependent on each other.

Example 6.4.7: Let $X = Y = \{e, f, g, h\}$, $\tau = \{X, \varphi, \{f\}, \{g, h\}, \{f, g, h\}\}$ and $\sigma = \{Y, \varphi, \{g\}, \{e, f\}, \{e, f, g\}\}$. Define $\mathfrak{a} : (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = e, \mathfrak{a}(f) = f, \mathfrak{a}(g) = g, \mathfrak{a}(h) = h$. Here \mathfrak{a} is $g\eta$ -continuous. But \mathfrak{a} is not rg -continuous, gpr -continuous, gar -continuous. Since for the closed set, $\{g, h\}$ in Y , $\mathfrak{a}^{-1}(\{g, h\}) = \{g, h\}$ is $g\eta$ -closed but not rg -closed, gpr -closed, gar -closed in X . Hence \mathfrak{a} is $g\eta$ -homeomorphism but not rg -homeomorphism, gpr -homeomorphism, gar -homeomorphism.

Example 6.4.8: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}\}$ and $\sigma = \{Y, \varphi, \{f, g\}\}$. Define $\mathfrak{a} : (X, \tau) \rightarrow (Y, \sigma)$ as $\mathfrak{a}(e) = e, \mathfrak{a}(f) = g, \mathfrak{a}(g) = f$. Here \mathfrak{a} is rg -continuous, gpr -continuous, gar -continuous. But \mathfrak{a} is not $g\eta$ -continuous. Since for the closed set, $\{e\}$ in Y , $\mathfrak{a}^{-1}(\{e\}) = \{e\}$ is rg -closed, gpr -closed, gar -closed but not $g\eta$ -closed in

X . Hence \mathfrak{a} is rg -homeomorphism, gpr -homeomorphism, gar -homeomorphism but not $g\eta$ -homeomorphism.

Remark 6.4.9: The composition of two $g\eta$ -homeomorphism need not be $g\eta$ -homeomorphism as seen from the following example.

Example 6.4.10: Let $X = Y = Z = \{e, f, g\}$, $\tau = \{X, \varphi, \{f, g\}\}$, $\sigma = \{Y, \varphi, \{e\}\}$ and $\mu = \{Z, \varphi, \{e\}, \{f, g\}\}$. Define $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = g$, $\mathfrak{a}(g) = e$ and $\mathfrak{b}: (Y, \sigma) \rightarrow (Z, \mu)$ be defined as $\mathfrak{b}(e) = f$, $\mathfrak{b}(f) = e$, $\mathfrak{b}(g) = g$. Then the function \mathfrak{a} and \mathfrak{b} are $g\eta$ -continuous but their composition $\mathfrak{b} \circ \mathfrak{a}: (X, \tau) \rightarrow (Z, \mu)$ is not $g\eta$ -continuous, since for the closed set $\{f, g\}$ in (Z, μ) , $(\mathfrak{b} \circ \mathfrak{a})^{-1}(\{f, g\}) = \{f, g\}$ is not $g\eta$ -closed in (X, τ) .

Theorem 6.4.11: Let $\mathfrak{a}: (X, \tau) \rightarrow (Y, \sigma)$ be a bijective and $g\eta$ -continuous map. Then the following statements are equivalent.

- (i) \mathfrak{a} is $g\eta$ -open map.
- (ii) \mathfrak{a} is $g\eta$ -homeomorphism.
- (iii) \mathfrak{a} is $g\eta$ -closed map.

Proof: (i) \Rightarrow (ii) Let F be a closed set in (X, τ) . Then $\{X - F\}$ is open in (X, τ) . Since \mathfrak{a} is $g\eta$ -open, then $\mathfrak{a}(X - F)$ is $g\eta$ -open in (Y, σ) . This implies $Y - \mathfrak{a}(F)$ is $g\eta$ -open in (Y, σ) . That is, $\mathfrak{a}(F)$ is $g\eta$ -closed in (Y, σ) . Thus \mathfrak{a} $g\eta$ -closed. Further $(\mathfrak{a}^{-1})^{-1}(F) = \mathfrak{a}(F)$ is $g\eta$ -closed in (Y, σ) . Thus \mathfrak{a}^{-1} $g\eta$ -continuous. By assumption \mathfrak{a} is $g\eta$ -continuous and bijective. Hence \mathfrak{a} is $g\eta$ -homeomorphism.

(ii) \Rightarrow (iii) Suppose \mathfrak{a} is a $g\eta$ -homeomorphism. Then \mathfrak{a} is bijective, \mathfrak{a} and \mathfrak{a}^{-1} are $g\eta$ -continuous. Let \mathfrak{a} be a closed set in (X, τ) . Since \mathfrak{a}^{-1} is $g\eta$ -continuous. Then $(\mathfrak{a}^{-1})^{-1}(F) = \mathfrak{a}(F)$ is $g\eta$ -closed in (Y, σ) . Thus \mathfrak{a} is $g\eta$ -closed.

(iii) \Rightarrow (i) Let \mathfrak{a} be a $g\eta$ -closed map. Let G be an open in X . Then $X - G$ is closed in (X, τ) . Since \mathfrak{a} is $g\eta$ -closed, $\mathfrak{a}(X - G)$ is $g\eta$ -closed in (Y, σ) . This implies $Y - \mathfrak{a}(G)$ is $g\eta$ -closed in (Y, σ) . Therefore $\mathfrak{a}(G)$ is $g\eta$ -open in (Y, σ) .

6.5 $xg\eta$ -CLOSED MAPS

In this section the concept of $xg\eta$ -closed maps are introduced and their basic properties are obtained.

Definition 6.5.1: A function $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ is said to be a $x\eta$ -closed map if the image of every closed set in (X, τ, \leq) is a $x\eta$ -closed set in (Y, σ, \leq) .

Definition 6.5.2: A function $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ is said to be a $xg\eta$ -closed map if the image of every closed set in (X, τ, \leq) is a $xg\eta$ -closed set in (Y, σ, \leq) .

Theorem 6.5.3: Every i -closed, $i\alpha$ -closed, $i\eta$ -closed maps are $ig\eta$ -closed map, but not conversely.

Proof: The proof follows from the fact that every i -closed, $i\alpha$ -closed, $i\eta$ -closed set is an $ig\eta$ -closed set [3.5.2, 3.5.6]. Then every i -closed, $i\alpha$ -closed, $i\eta$ -closed maps are $ig\eta$ -closed map.

Example 6.5.4: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{f\}, \{e, f\}\}$ and $\sigma = \{Y, \varphi, \{e\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, f), (g, f)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = e$, $\mathfrak{a}(f) = g$, $\mathfrak{a}(g) = f$. This map is $ig\eta$ -closed map, but not i -closed, $i\alpha$ -closed, $i\eta$ -closed map. Since for the closed set $W = \{e, g\}$ in (X, τ, \leq) , $\mathfrak{a}(W) = \{e, f\}$ is $ig\eta$ -closed but not i -closed, $i\alpha$ -closed, $i\eta$ -closed in (Y, σ, \leq) .

Theorem 6.5.5: Every d -closed, $d\alpha$ -closed, $d\eta$ -closed maps are $dg\eta$ -closed map, but not conversely.

Proof: The proof follows from the fact that every d -closed, $d\alpha$ -closed, $d\eta$ -closed sets are $dg\eta$ -closed set [3.5.8, 3.5.10]. Then every d -closed, $d\alpha$ -closed, $d\eta$ -closed maps are $dg\eta$ -closed map.

Example 6.5.6: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f, g\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, f), (f, g), (e, g)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$

by $\mathfrak{a}(e) = g$, $\mathfrak{a}(f) = f$, $\mathfrak{a}(g) = e$. This map is $d\eta$ -closed map, but not d -closed, $d\alpha$ -closed, $d\eta$ -closed map, since for the closed set $W = \{f, g\}$ in (X, τ, \leq) , $\mathfrak{a}(W) = \{e, f\}$ is $d\eta$ -closed but not d -closed, $d\alpha$ -closed, $d\eta$ -closed in (Y, σ, \leq) .

Theorem 6.5.7: Every b -closed, $b\alpha$ -closed maps are $b\eta$ -closed map, but not conversely.

Proof: The proof follows from the fact that every b -closed, $b\alpha$ -closed sets are $b\eta$ -closed set [3.5.14]. Then every b -closed, $b\alpha$ -closed maps are $b\eta$ -closed map.

Example 6.5.8: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{f, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f\}, \{e, f\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, g)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$. This map is $b\eta$ -closed map, but not b -closed, $b\alpha$ -closed map, since for the closed set $W = \{e\}$ in (X, τ, \leq) , $\mathfrak{a}(W) = \{f\}$ is $b\eta$ -closed but not b -closed, $b\alpha$ -closed in (Y, σ, \leq) .

Theorem 6.5.9: Every $b\eta$ -closed map is $b\eta$ -closed map, but not conversely.

Proof: The proof follows from the fact that every $b\eta$ -closed set is $b\eta$ -closed set [3.5.18]. Then every $b\eta$ -closed maps are $b\eta$ -closed map.

Example 6.5.10: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{f, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, g)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$. This map is $b\eta$ -closed map, but not $b\eta$ -closed map, since for the closed set $W = \{f, g\}$ in (X, τ, \leq) , $\mathfrak{a}(W) = \{e, g\}$ is $b\eta$ -closed but not $b\eta$ -closed in (Y, σ, \leq) .

6.6 $x\eta$ -OPEN MAPS

Definition 6.6.1: A function $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ is said to be a $x\eta$ -open map if the image of every open set in (X, τ, \leq) is a $x\eta$ -open set in (Y, σ, \leq) .

Definition 6.6.2: A map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ is said to be a $x\eta$ -open map if the image of every open set in (X, τ, \leq) is a $x\eta$ -open set in (Y, σ, \leq) .

Theorem 6.6.3: Every i -open, $i\alpha$ -open, $i\eta$ -open maps are $ig\eta$ -open map, but not conversely.

Proof: The proof follows from the fact that every i -open, $i\alpha$ -open, $i\eta$ -open sets are $ig\eta$ -open set [3.5.2, 3.5.6]. Then every i -open, $i\alpha$ -open, $i\eta$ -open maps are $ig\eta$ -open map.

Example 6.6.4: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{f, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f, g\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, f), (f, g), (e, g)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = g$, $\mathfrak{a}(f) = f$, $\mathfrak{a}(g) = e$. This map is $ig\eta$ -open map, but not i -open, $i\alpha$ -open, $i\eta$ -open map, since for the open set $W = \{f, g\}$ in (X, τ, \leq) , $\mathfrak{a}(W) = \{e, f\}$ is $ig\eta$ -open but not i -open, $i\alpha$ -open, $i\eta$ -open in (Y, σ, \leq) .

Theorem 6.6.5: Every d -open, $d\alpha$ -open maps are $dg\eta$ -open map, but not conversely.

Proof: The proof follows from the fact that every d -open, $d\alpha$ -open sets are $dg\eta$ -open set [3.5.8]. Then every d -open, $d\alpha$ -open maps are $dg\eta$ -open map.

Example 6.6.6: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e, f\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f\}, \{e, f\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, f), (g, f)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = g$, $\mathfrak{a}(f) = f$, $\mathfrak{a}(g) = e$. This map is $dg\eta$ -open map, but not d -open, $d\alpha$ -open map, since for the open set $W = \{e, f\}$ in (X, τ, \leq) , $\mathfrak{a}(W) = \{f, g\}$ is $dg\eta$ -open but not d -open, $d\alpha$ -open in (Y, σ, \leq) .

Theorem 6.6.7: Every $d\eta$ -open map is $dg\eta$ -open map, but not conversely.

Proof: The proof follows from the fact that every $d\eta$ -open set is $dg\eta$ -open set [3.5.10]. Then every $d\eta$ -open map is $dg\eta$ -open map.

Example 6.6.8: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{g\}\}$ and $\sigma = \{Y, \varphi, \{e\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, f), (g, f)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = g$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = f$. This map is $dg\eta$ -open map, but not $d\eta$ -open map, since for the open set $W = \{g\}$ in (X, τ, \leq) , $\mathfrak{a}(W) = \{f\}$ is $dg\eta$ -open but not $d\eta$ -open in (Y, σ, \leq) .

Theorem 6.6.9: Every b -open, $b\alpha$ -open maps are $bg\eta$ -open map, but not conversely.

Proof: The proof follows from the fact that every b -open, $b\alpha$ -open sets are $bg\eta$ -open set [3.5.14]. Then every b -open, $b\alpha$ -open maps are $bg\eta$ -open map.

Example 6.6.10: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{f, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f\}, \{e, f\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, g)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$. This map is $bg\eta$ -open map, but not b -open, $b\alpha$ -open map, since for the open set $W = \{f, g\}$ in (X, τ, \leq) , $\mathfrak{a}(W) = \{e, g\}$ is $bg\eta$ -open but not b -open, $b\alpha$ -open in (Y, σ, \leq) .

Theorem 6.6.11: Every $b\eta$ -open map is $bg\eta$ -open map, but not conversely.

Proof: The proof follows from the fact that every $b\eta$ -open set is $bg\eta$ -open set [3.5.18]. Then every $b\eta$ -open map is $bg\eta$ -open map.

Example 6.6.12: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{f, g\}\}$ and $\sigma = \{Y, \varphi, \{e\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, g)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$. This map is $bg\eta$ -open map, but not $b\eta$ -open map, since for the open set $W = \{e\}$ in (X, τ, \leq) , $\mathfrak{a}(W) = \{f\}$ is $bg\eta$ -open but not $b\eta$ -open in (Y, σ, \leq) .

6.7 $xg\eta$ -HOMEOMORPHISM

Definition 6.7.1: A bijection map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ is called $x\eta$ -homeomorphism if \mathfrak{a} is both $x\eta$ -continuous map and $x\eta$ -open map.

Definition 6.7.2: A bijection map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ is called $xg\eta$ -homeomorphism if \mathfrak{a} is both $xg\eta$ -continuous map and $xg\eta$ -open map.

Theorem 6.7.3: Every i -homeomorphism, $i\alpha$ -homeomorphism, maps are $ig\eta$ -homeomorphism map, but not conversely.

Proof: The proof follows from the fact that every i -continuous, $i\alpha$ -continuous, maps are $ig\eta$ -continuous map [4.4.3, 4.4.5]. Also every i -open map, $i\alpha$ -open maps are $ig\eta$ -open map [6.6.3].

Example 6.7.4: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{f\}, \{e, f\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f, g\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, g)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$. This map is $ig\eta$ -continuous, but not an i -continuous, $i\alpha$ -continuous, since for the closed set $W = \{e\}$ in (Y, σ, \leq) , $\mathfrak{a}^{-1}(W) = \{f\}$ is $ig\eta$ -closed but not an i -closed, $i\alpha$ -closed in (X, τ, \leq) .

Theorem 6.7.5: Every $i\eta$ -homeomorphism map is $ig\eta$ -homeomorphism map, but not conversely.

Proof: The proof follows from the fact that every $i\eta$ -continuous map is $ig\eta$ -continuous map [4.4.5]. Also every $i\eta$ -open map is $ig\eta$ -open map [6.6.3].

Example 6.7.6: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f, g\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, g)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$. This map is $ig\eta$ -continuous, but not an $i\eta$ -continuous, since for the closed set $W = \{f, g\}$ in (Y, σ, \leq) , $\mathfrak{a}^{-1}(W) = \{e, g\}$ is not $i\eta$ -closed in (X, τ, \leq) .

Theorem 6.7.7: Every d -homeomorphism, $d\alpha$ -homeomorphism maps are $dg\eta$ -homeomorphism map, but not conversely.

Proof: The proof follows from the fact that every d -continuous, $d\alpha$ -continuous maps are $dg\eta$ -continuous map [4.4.9]. Also every d -open map, $d\alpha$ -open maps are $dg\eta$ -open map [6.6.5].

Example 6.7.8: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{f\}, \{e, f\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f, g\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, g)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$. This map is $dg\eta$ -continuous, but not d -continuous, $d\alpha$ -continuous, since for the closed set $W = \{e\}$ in (Y, σ, \leq) , $\mathfrak{a}^{-1}(W) = \{f\}$ is d $g\eta$ -closed but not d -closed, $d\alpha$ -closed in (X, τ, \leq) .

Theorem 6.7.9: Every $d\eta$ -homeomorphism map is $dg\eta$ -homeomorphism map, but not conversely.

Proof: The proof follows from the fact that every $d\eta$ -continuous maps are $dg\eta$ -continuous map [4.4.9]. Also every $d\eta$ -open map is are $dg\eta$ -open map [6.6.7].

Example 6.7.10: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f, g\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, g)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$. This map is $dg\eta$ -continuous, but not $d\eta$ -continuous, since for the closed set $W = \{f, g\}$ in (Y, σ, \leq) , $\mathfrak{a}^{-1}(W) = \{e, g\}$ is $dg\eta$ -closed but not $d\eta$ -closed in (X, τ, \leq) .

Theorem 6.7.11: Every $b\alpha$ -homeomorphism, $b\eta$ -homeomorphism, maps are $bg\eta$ -homeomorphism map, but not conversely.

Proof: The proof follows from the fact that every $b\alpha$ -continuous, $b\eta$ -continuous maps are $bg\eta$ -continuous map [4.4.11]. Also every $b\alpha$ -open map, $b\eta$ -open maps are $bg\eta$ -open map [6.6.9, 6.6.11].

Example 6.7.12: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f, g\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, g)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$. This map is $bg\eta$ -continuous, but not $b\alpha$ -continuous, $b\eta$ -continuous, since for the closed set $W = \{f, g\}$ in (Y, σ, \leq) , $\mathfrak{a}^{-1}(W) = \{e, g\}$ is $bg\eta$ -closed but not b semi-closed, $b\alpha$ -closed, $b\eta$ -closed in (X, τ, \leq) .

Theorem 6.7.13: Every b -homeomorphism map is $bg\eta$ -homeomorphism map, but not conversely.

Proof: The proof follows from the fact that every b -continuous map is $bg\eta$ -continuous map [4.4.11]. Also every b -open map is $bg\eta$ -open map [6.6.9].

Example 6.7.14: Let $X = Y = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{f\}, \{e, f\}\}$ and $\sigma = \{Y, \varphi, \{e\}, \{f, g\}\}$, $\leq = \{(e, e), (f, f), (g, g), (e, g)\}$. Define a map $\mathfrak{a}: (X, \tau, \leq) \rightarrow (Y, \sigma, \leq)$ by $\mathfrak{a}(e) = f$, $\mathfrak{a}(f) = e$, $\mathfrak{a}(g) = g$. This map is $bg\eta$ -continuous, but not b -continuous, since for the closed set $W = \{e\}$ in (Y, σ, \leq) , $\mathfrak{a}^{-1}(W) = \{f\}$ is $bg\eta$ -closed but not b -closed in (X, τ, \leq) .

CHAPTER-7

***gη*-SEPARATION AXIOMS IN TOPOLOGICAL SPACES**

7.1. INDRODUCTION

In 1943, Shamin [97] introduced the separation axioms in topological spaces. Ekici, Jafari, Kar and Bhattacharyya [37, 46, 50] introduced some weak separation axioms in topological spaces. Many authors [1, 3, 9, 17, 18, 53, 73] contributed much to develop the separation axioms to the topological spaces.

In this chapter, a new class of separation axioms in topological spaces using *gη*-closed sets are framed. Also the concept of *gη-T_k* spaces for $k = 0, 1, 2$ *gη-D_k* spaces for $k = 0, 1, 2$ and *gη-R_k* spaces for $k = 0, 1$ and some of their properties are also investigated.

7.2. *gη*-SEPARATION AXIOMS

Definition 7.2.1: A topological space (X, τ) is said to be

(i) *gηT₀* if for each pair of distinct points k, l in X , there exists a *gη*-open set G such that either $k \in G$ and $l \notin G$ or $k \notin G$ and $l \in G$.

(ii) *gηT₁* if for each pair of distinct points k, l in X , there exists two *gη*-open sets G and H such that $k \in G$ but $l \notin G$ and $l \in H$ but $k \notin H$.

(iii) *gηT₂* if for each pair of distinct points k, l in X , there exists two disjoint *gη*-open sets G and H containing k and l respectively.

Example 7.2.2: (i). Let $X = \{e, f, g\}$, $\tau = \{X, \varphi, \{f, g\}\}$. Here *gη*-open sets are $\{X, \varphi, \{f\}, \{g\}, \{f, g\}\}$. Since for the distinct points f and g , there exists a *gη*-open set $G = \{f\}$ such that $f \in G$ and $g \notin G$ or $G = \{g\}$ such that $f \notin G$ and $g \in G$. Therefore X is *gηT₀* space.

(ii) Let $X = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}\}$. Here *gη*-open sets are $\{X, \varphi, \{e\}, \{f\}, \{g\}, \{e, f\}, \{e, g\}\}$. Since for the distinct points e and g , there exists two *gη*-open sets

$G = \{e\}$ and $H = \{g\}$ such that $e \in G$ but $g \notin G$ and $e \notin H$ but $g \in H$. In a similar manner other pairs of distinct points may also be discussed. Therefore X is $g\eta T_1$ space.

(iii) Let $X = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}\}$. Here $g\eta$ -open sets are $\{X, \varphi, \{e\}, \{f\}, \{g\}, \{e, f\}, \{e, g\}\}$. Since for the distinct points e and g , there exists two disjoint $g\eta$ -open set $G = \{e\}$ and $H = \{g\}$ containing $\{e\}$ and $\{g\}$ satisfying $g\eta T_2$ conditions. And this is true for other pair of distinct points. Therefore X is $g\eta T_2$ space.

Remark 7.2.3: Let (X, τ) be a topological space, then the following are true:

(i) Every $g\eta T_2$ space is $g\eta T_1$.

(ii) Every $g\eta T_1$ space is $g\eta T_0$.

Theorem 7.2.4: A topological space (X, τ) is $g\eta T_0$ if and only if for any two distinct points k, l of X , $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$.

Proof: Necessity: Let (X, τ) be a $g\eta T_0$ space and k, l be any two distinct points of X . There exists a $g\eta$ -open set G containing k or l , say k but not l . Then $X - G$ is a $g\eta$ -closed set which does not contain k but contains l . Since $g\eta cl(\{l\})$ is the smallest $g\eta$ -closed set containing l , $g\eta cl(\{l\}) \subseteq X - G$ and therefore $k \notin g\eta cl(\{l\})$. Consequently $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$.

Sufficiency: Suppose that $k, l \in X$, $k \neq l$ and $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$. Let m be a point of X such that $m \in g\eta cl(\{k\})$ but $m \notin g\eta cl(\{l\})$. We claim that $k \notin g\eta cl(\{l\})$. For if $k \in g\eta cl(\{l\})$ then $g\eta cl(\{k\}) \subseteq g\eta cl(\{l\})$. This contradicts the fact that $m \notin g\eta cl(\{l\})$. Consequently k belongs to the $g\eta$ -open set $X - g\eta cl(\{l\})$ to which l does not belong to. Hence (X, τ) is a $g\eta T_0$ space.

Theorem 7.2.5: In a topological space (X, τ) , if the singletons are $g\eta$ -closed then X is $g\eta T_1$ space and the converse is true if $G\eta O(X, \tau)$ is closed under arbitrary union.

Proof: Let $\{m\}$ is $g\eta$ -closed for every $m \in X$. Let $k, l \in X$ with $k \neq l$. Now $k \neq l$ implies $l \in X - \{k\}$. Hence $X - \{k\}$ is a $g\eta$ -open set that contains l but not k . Similarly $X - \{l\}$ is a $g\eta$ -open set containing k but not l . Therefore X is a $g\eta T_1$ space.

Conversely, let (X, τ) be $g\eta T_1$ and k be any point of X . Choose $l \in X - \{k\}$ then $k \neq l$ and so there exists a $g\eta$ -open set G such that $l \in G$ but $k \notin G$. Consequently $l \in G \subseteq X - \{k\}$, that is $X - \{k\} = \bigcup \{U_l : l \in X - \{k\}\}$ which is $g\eta$ -open. Hence $\{k\}$ is $g\eta$ -closed. Hence the result is true for any singleton set.

Theorem 7.2.6: For a topological space (X, τ) . The following results are equivalent to each other.

(i) X is $g\eta T_2$.

(ii) Let $k \in X$. For each $l \neq k$, there exists a $g\eta$ -open set G containing k such that $l \notin g\eta cl(\{G\})$.

(iii) For each $k \in X$, $\bigcap \{g\eta cl(\{G\}) : G \in G\eta O(X, \tau) \text{ and } k \in G\} = \{k\}$.

Proof: (i) \Rightarrow (ii) Let $k \in X$, and for any $l \in X$ such that $k \neq l$, there exists disjoint $g\eta$ -open sets G and H containing k and l respectively, since X is $g\eta T_2$. So $G \subseteq X - H$. Therefore, $g\eta cl(\{G\}) \subseteq X - H$. So $l \notin g\eta cl(\{G\})$.

(ii) \Rightarrow (iii) If possible for some $l \neq k$, $l \in \bigcap \{g\eta cl(\{G\}) : G \in G\eta O(X, \tau) \text{ and } k \in G\}$. This implies $l \in g\eta cl(\{G\})$ for every $g\eta$ -open set G containing k , which contradicts (ii) Hence $\bigcap \{g\eta cl(\{G\}) : G \in G\eta O(X, \tau) \text{ and } k \in G\} = \{k\}$.

(iii) \Rightarrow (i) Let $k, l \in X$ and $k \neq l$. Then there exists at least one $g\eta$ -open set G containing k such that $l \notin g\eta cl(\{G\})$. Let $H = X - g\eta cl(\{G\})$, then $l \in H$ and $k \in G$ and also $G \cap H = \emptyset$. Therefore X is $g\eta T_2$.

Definition 7.2.7: A subset R of a topological space X is called a $g\eta$ -difference set (briefly $g\eta D$ set) if there exists $G, H \in G\eta O(X, \tau)$ such that $G \neq X$ and $R = G - H$.

Theorem 7.2.8: Every proper $g\eta$ -open set is a $g\eta D$ set.

Proof: Let G be a $g\eta$ -open set different from X . Take $H = \varphi$. Then $G = G - H$ is a $g\eta D$ set. But, the converse is not true as seen in the following example.

Example 7.2.9: Let $X = \{e, f, g\}$, $\tau = \{X, \varphi, \{e\}, \{g\}, \{e, g\}\}$. Here $g\eta$ -open sets are $\{X, \varphi, \{e\}, \{g\}, \{e, f\}, \{e, g\}, \{f, g\}\}$ then $G = \{e, f\} \neq X$ and $H = \{e, g\}$ are $g\eta$ -open sets in X . Let $R = G - H = \{e, f\} - \{e, g\} = \{f\}$. Then $R = \{f\}$ is a $g\eta D$ set but it is not $g\eta$ -open.

Definition 7.2.10: A topological space (X, τ) is said to be

(i) $g\eta D_0$ if for any pair of distinct points k and l of X there exists a $g\eta D$ set of X containing k but not l or a $g\eta D$ set of X containing l but not k .

(ii) $g\eta D_1$ if for any pair of distinct points k and l of X there exists a $g\eta D$ set of X containing k but not l and a $g\eta D$ set of X containing l but not k .

(iii) $g\eta D_2$ if for any pair of distinct points k and l of X there exists two disjoint $g\eta D$ sets of X containing k and l respectively.

Remark 7.2.11: For a topological space (X, τ) , the following properties are hold:

(i) If (X, τ) is $g\eta T_i$, then it is $g\eta D_i$, for $i = 0, 1, 2$.

(ii) If (X, τ) is $g\eta D_i$, then it is $g\eta D_{i-1}$, for $i = 1, 2$.

Theorem 7.2.12: A topological space (X, τ) is $g\eta D_0$ if and only if it is $g\eta T_0$.

Proof: Suppose that X is $g\eta D_0$. Then for each distinct pair $k, l \in X$, at least one of k, l say k belongs to a $g\eta D$ set Q but $l \notin Q$. As Q is $g\eta D$ set. Let $Q = G_1 - G_2$ where $G_1 \neq X$ and $G_1, G_2 \in G\eta O(X, \tau)$. Then $k \in G_1$, and for $l \notin Q$ we have two cases: (i) $l \notin G_1$, (ii) $l \in G_1$ and $l \in G_2$. In case (i), $k \in G_1$ but $l \notin G_1$. In case (ii), $l \in G_2$ but $k \notin G_2$. Thus in the both the cases, we obtain that X is $g\eta T_0$.

Conversely, if X is $g\eta T_0$, by Remark 7.2.11(i) X is $g\eta D_0$.

Theorem 7.2.13: Suppose $G\eta O(X, \tau)$ is closed under arbitrary union, then X is $g\eta D_1$ if and only if it is $g\eta D_2$.

Proof: Necessity: Let $k, l \in X$ and $k \neq l$. Then there exist two $g\eta D$ sets Q_1, Q_2 in X such that $k \in Q_1, l \notin Q_1$ and $l \in Q_2, k \notin Q_2$. Let $Q_1 = G_1 - G_2$ and $Q_2 = G_3 - G_4$, where G_1, G_2, G_3 and G_4 are $g\eta$ -open sets in X . From $k \notin Q_2$, the following two cases arise: Case (i): $k \notin G_3$. Case (ii): $k \in G_3$ and $k \in G_4$.

Case (i) $k \notin G_3$. By $l \notin Q_1$ we have two sub cases:

(a) $l \notin G_1$. Since $k \in G_1 - G_2$, it follows that $k \in G_1 - (G_2 \cup G_3)$, and since $l \in G_3 - G_4$ we have $l \in G_3 - (G_1 \cup G_4)$, and $(G_1 - (G_2 \cup G_3)) \cap (G_3 - (G_1 \cup G_4)) = \varphi$.

(b) $l \in G_1$ and $l \in G_2$. We have $k \in G_1 - G_2$ and $l \in G_2$, and $(G_1 - G_2) \cap G_2 = \varphi$.

Case (ii) $k \in G_3$ and $k \in G_4$. We have $l \in G_3 - G_4$ and $k \in G_4$. Hence $(G_3 - G_4) \cap G_4 = \varphi$. Thus both case (i) and in case (ii), X is $g\eta D_2$.

Sufficiency: Follows from Remark 7.2.11(ii).

Corollary 7.2.14: If a topological space (X, τ) is $g\eta D_1$, then it is $g\eta T_0$.

Proof: Follows from 7.2.11(ii) and theorem 7.2.12.

Definition 7.2.15: A point $k \in X$ which has only X as the $g\eta$ -neighbourhood is called a $g\eta$ -neat point.

Proposition 7.2.16: For a $g\eta T_0$ topological space (X, τ) which has atleast two elements, the following results are equivalent:

(i) (X, τ) is $g\eta D_1$ space.

(ii) (X, τ) has no $g\eta$ -neat point.

Proof: (i) \Rightarrow (ii) Since (X, τ) is a $g\eta D_1$ space then each point k of X is contained in a $g\eta D$ set $R = G - H$ and thus in G . By definition $G \neq X$. This implies that k is not a $g\eta$ -neat point. Therefore (X, τ) has no $g\eta$ -neat point.

(ii) \Rightarrow (i) Let X be a $g\eta T_0$ space, then for each distinct pair of points $k, l \in X$, atleast one of them, k (say) has a $g\eta$ -neighbourhood G containing k and not l . Thus G which

is different from X is a $g\eta D$ set. If X has no $g\eta$ -neat point, then l is not $g\eta$ -neat point. This means that there exists a $g\eta$ -neighbourhood H of l such that $H \neq X$. Thus $l \in H - G$ but not k and $H - G$ is a $g\eta D$ set. Hence X is $g\eta D_1$.

Definition 7.2.17: A topological space (X, τ) is said to be $g\eta$ -symmetric if for any pair of distinct points k and l in X , $k \in g\eta cl(\{l\})$ implies $l \in g\eta cl(\{k\})$.

Theorem 7.2.18: If (X, τ) is a topological space, then the following are equivalent:

(i) (X, τ) is a $g\eta$ -symmetric space.

(ii) $\{k\}$ is $g\eta$ -closed, for each $k \in X$.

Proof: (i) \Rightarrow (ii) Let (X, τ) be a $g\eta$ -symmetric space. Assume that $\{k\} \subseteq G \in G\eta O(X, \tau)$, but $g\eta cl(\{k\}) \not\subseteq G$. Then $g\eta cl(\{k\}) \cap (X - G) \neq \emptyset$. Now, we take $l \in g\eta cl(\{k\}) \cap (X - G)$, then by hypothesis $k \in g\eta cl(\{l\}) \subseteq X - G$ that is, $k \notin G$, which is contradiction. Therefore $\{k\}$ is $g\eta$ -closed, for each $k \in X$.

(ii) \Rightarrow (i) Assume that $k \in g\eta cl(\{l\})$, but $l \notin g\eta cl(\{k\})$. Then $\{l\} \subseteq X - g\eta cl(\{k\})$ and hence $g\eta cl(\{l\}) \subseteq X - g\eta cl(\{k\})$. Therefore $k \in X - g\eta cl(\{k\})$, which is contradiction and hence $l \in g\eta cl(\{k\})$.

Corollary 7.2.19: Let $G\eta O(X, \tau)$ be closed under arbitrary union. If the topological space (X, τ) is a $g\eta T_1$ space, then it is $g\eta$ -symmetric.

Proof: In a $g\eta T_1$ space, every singleton set is $g\eta$ -closed by theorem 7.2.5 therefore, by theorem 7.2.18, (X, τ) is $g\eta$ -symmetric.

Corollary 7.2.20: If a topological space (X, τ) is $g\eta$ -symmetric and $g\eta T_0$, then (X, τ) is a $g\eta T_1$ space.

Proof: Let $k \neq l$ and as (X, τ) is $g\eta T_0$, we may assume that $k \in G \subseteq X - \{l\}$ for some $G \in G\eta O(X, \tau)$. Then $k \notin g\eta cl(\{l\})$ and hence $l \notin g\eta cl(\{k\})$. There exists a $g\eta$ -open set H such that $l \in H \subseteq X - \{k\}$ and thus (X, τ) is a $g\eta T_1$ space.

Corollary 7.2.21: For a $g\eta$ -symmetric space (X, τ) , the following are equivalent:

(i) (X, τ) is $g\eta T_0$ space.

(ii) (X, τ) is $g\eta D_1$ space.

(iii) (X, τ) is $g\eta T_1$ space.

Proof: (i) \Rightarrow (iii) Follows from corollary 7.2.20.

(iii) \Rightarrow (ii) \Rightarrow (i) Follows from Remark 7.2.11 and Corollary 7.2.14.

Definition 7.2.22: A topological space (X, τ) is said to be $g\eta R_0$ if G is a $g\eta$ -open set and $k \in G$ then $g\eta cl(\{k\}) \subseteq G$.

Theorem: 7.2.23 For a topological space (X, τ) the following properties are equivalent to each other.

(i) (X, τ) is a $g\eta R_0$ space.

(ii) For any subset $Q \in G\eta C(X, \tau)$, $k \notin Q$ implies $Q \subseteq G$ and $k \notin G$ for some $G \in G\eta O(X, \tau)$.

(iii) For any subset $Q \in G\eta C(X, \tau)$, $k \notin Q$ implies $Q \cap g\eta cl(\{k\}) = \varphi$.

(iv) For any two distinct points k and l of X , either $g\eta cl(\{k\}) = g\eta cl(\{l\})$ or $g\eta cl(\{k\}) \cap g\eta cl(\{l\}) = \varphi$.

Proof: (i) \Rightarrow (ii) Let $Q \in G\eta C(X, \tau)$ and $k \notin Q$. Then by (i) $g\eta cl(\{k\}) \subseteq X - Q$. Set $G = X - g\eta cl(\{k\})$, then G is a $g\eta$ -open set such that $Q \subseteq G$ and $k \notin G$.

(ii) \Rightarrow (iii) Let $Q \in G\eta C(X, \tau)$ and $k \notin Q$. There exists $G \in G\eta O(X, \tau)$ such that $Q \subseteq G$ and $k \notin G$. Since $G \in G\eta O(X, \tau)$, $G \cap g\eta cl(\{k\}) = \varphi$ and $Q \cap g\eta cl(\{k\}) = \varphi$.

(iii) \Rightarrow (iv) Suppose that $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$ for two distinct points $k, l \in X$. There exists $m \in g\eta cl(\{k\})$ such that $m \notin g\eta cl(\{l\})$ [or $m \in g\eta cl(\{l\})$ such that $m \notin g\eta cl(\{k\})$]. There exists $H \in G\eta O(X, \tau)$ such that $l \notin H$ and $m \in H$, hence $k \in H$. Therefore, we have $k \notin g\eta cl(\{l\})$. By (iii), we obtain $g\eta cl(\{k\}) \cap g\eta cl(\{l\}) = \varphi$.

(iv) \Rightarrow (i) Let $H \in \mathcal{G}\eta\mathcal{O}(X, \tau)$ and $k \in H$. For each $l \notin H$, $k \neq l$ and $k \notin g\eta cl(\{l\})$. This shows that $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$. By (iv) $g\eta cl(\{k\}) \cap g\eta cl(\{l\}) = \varphi$ for each $l \in X - H$ and hence $g\eta cl(\{k\}) \cap [\cup g\eta cl(\{l\}): l \in X - H] = \varphi$. On the other hand, since $H \in \mathcal{G}\eta\mathcal{O}(X, \tau)$ and $l \in X - H$, we have $g\eta cl(\{l\}) \subseteq X - H$ and hence $X - H = \cup \{g\eta cl(\{l\}): l \in X - H\}$. Therefore, we obtain $(X - H) \cap g\eta cl(\{k\}) = \varphi$ and $g\eta cl(\{k\}) \subseteq H$. This shows that (X, τ) is a $g\eta R_0$ space.

Theorem 7.2.24: Let (X, τ) be a topological space. If it is $g\eta T_0$ space and $g\eta R_0$ space then it becomes a $g\eta T_1$ space.

Proof: Let k and l be any two distinct points of X . Since X is $g\eta T_0$, there exists a $g\eta$ -open set G such that $k \in G$ and $l \notin G$. As $k \in G$, implies that $g\eta cl(\{k\}) \subseteq G$. Since $l \notin G$, so $l \notin g\eta cl(\{k\})$. Hence $l \in H = X - g\eta cl(\{k\})$ and it is clear that $k \notin H$. Hence it follows that there exists a $g\eta$ -open sets G and H containing k and l respectively, such that $l \notin G$ and $k \notin H$. This implies that X is $g\eta T_1$ space.

Theorem 7.2.25: For a topological space (X, τ) the following properties are equivalent:

(i) (X, τ) is $g\eta R_0$ space.

(ii) $k \in g\eta cl(\{l\})$ if and only if $l \in g\eta cl(\{k\})$, for any two points k and l in X .

Proof: (i) \Rightarrow (ii) Assume that X is $g\eta R_0$. Let $k \in g\eta cl(\{l\})$ and H be any $g\eta$ -open set such that $l \in H$. Now by hypothesis, $k \in H$. Therefore, every $g\eta$ -open set which contain l contains k . Hence $l \in g\eta cl(\{k\})$.

(ii) \Rightarrow (i) Let G be a $g\eta$ -open set and $k \in G$. If $l \notin G$, then $k \notin g\eta cl(\{l\})$ and hence $l \notin g\eta cl(\{k\})$. This implies that $g\eta cl(\{k\}) \subseteq G$. Hence (X, τ) is $g\eta R_0$ space.

Remark 7.2.26: From Definition 7.2.17 and theorem 7.2.25 the notion of $g\eta$ -symmetric and $g\eta R_0$ are equivalent.

Theorem 7.2.27: A topological space (X, τ) is $g\eta R_0$ space if and only if for any two points k and l in X , $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$ implies $g\eta cl(\{k\}) \cap g\eta cl(\{l\}) = \varphi$.

Proof: Necessity: Suppose that (X, τ) is $g\eta R_0$ and k and $l \in X$ such that $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$. Then, there exists $m \in g\eta cl(\{k\})$ such that $m \notin g\eta cl(\{l\})$ [or $m \in g\eta cl(\{l\})$ such that $m \notin g\eta cl(\{k\})$]. There exists $H \in G\eta O(X, \tau)$ such that $l \notin H$ and $m \in H$, hence $k \in H$. Therefore, we have $k \notin g\eta cl(\{l\})$. Thus $k \in [X - g\eta cl(\{l\})] \in G\eta O(X, \tau)$, which implies $g\eta cl(\{k\}) \subseteq [X - g\eta cl(\{l\})]$ and $g\eta cl(\{k\}) \cap g\eta cl(\{l\}) = \varphi$.

Sufficiency: Let $H \in G\eta O(X, \tau)$ and let $k \in H$. To show that $g\eta cl(\{k\}) \subseteq H$. Let $l \notin H$, that is $l \in X - H$. Then $k \neq l$ and $k \notin g\eta cl(\{l\})$. This shows that $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$. By assumption, $g\eta cl(\{k\}) \cap g\eta cl(\{l\}) = \varphi$. Hence $l \notin g\eta cl(\{k\})$ and therefore $g\eta cl(\{k\}) \subseteq H$. Hence (X, τ) is $g\eta R_0$ space.

Definition 7.2.28: A topological space (X, τ) is said to be $g\eta R_1$ if for k, l in X with $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$, there exists disjoint $g\eta$ -open sets G and H such that $g\eta cl(\{k\}) \subseteq G$ and $g\eta cl(\{l\}) \subseteq H$.

Theorem 7.2.29: For a topological space (X, τ) . Every $g\eta T_2$ space is $g\eta R_1$ space.

Proof: Let k and l be any two points X such that $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$. By Remark 7.2.3(i), every $g\eta T_2$ space is a $g\eta T_1$ space. Therefore, by theorem 7.2.5, $g\eta cl(\{k\}) = \{k\}$, $g\eta cl(\{l\}) = \{l\}$ and hence $\{k\} \neq \{l\}$. Since (X, τ) is $g\eta T_2$, there exists disjoint $g\eta$ -open sets G and H such that $g\eta cl(\{k\}) = \{k\} \subseteq G$ and $g\eta cl(\{l\}) = \{l\} \subseteq H$. Therefore (X, τ) is $g\eta R_1$ space.

Theorem 7.2.30: If a topological space (X, τ) is $g\eta$ -symmetric, then the following are equivalent:

- (i) (X, τ) is $g\eta T_2$ space.
- (ii) (X, τ) is $g\eta R_1$ space and $g\eta T_1$ space.
- (iii) (X, τ) is $g\eta R_1$ space and $g\eta T_0$ space.

Proof: (i). \Rightarrow (ii) and (ii) \Rightarrow (iii) obvious.

(iii). \Rightarrow (i) Let k and l be two disjoint points of X . Since (X, τ) is a $g\eta T_0$ space, by theorem 7.2.4, $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$. Since X is $g\eta R_1$, there exists a disjoint $g\eta$ -open sets G and H such that $g\eta cl(\{k\}) \subseteq G$ and $g\eta cl(\{l\}) \subseteq H$. Therefore, there exists disjoint $g\eta$ -open sets G and H such that $k \in G$ and $l \in H$. Hence (X, τ) is a $g\eta T_2$ space.

Remark 7.2.31: For a topological space (X, τ) the following statements are equivalent:

(i) (X, τ) is $g\eta R_1$ space.

(ii) If $k, l \in X$ such that $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$, then there exists $g\eta$ -closed sets Q_1 and Q_2 such that $k \in Q_1, l \notin Q_1, l \in Q_2, k \notin Q_2, X = Q_1 \cup Q_2$.

Theorem 7.2.32: If a topological space (X, τ) is $g\eta R_1$ space, then (X, τ) is $g\eta R_0$ space.

Proof: Let G be a $g\eta$ -open set such that $k \in G$. If $l \notin G$, then $k \notin g\eta cl(\{l\})$, therefore $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$. So there exists a $g\eta$ -open set H such that $g\eta cl(\{l\}) \subseteq H$ and $k \notin H$, which implies $l \notin g\eta cl(\{k\})$. Hence $g\eta cl(\{k\}) \subseteq G$. Therefore, (X, τ) is $g\eta R_0$ space.

Theorem 7.2.33: A topological space (X, τ) is $g\eta R_1$ space if and only if $k \in X - g\eta cl(\{l\})$ implies that k and l have disjoint $g\eta$ -open neighbourhoods.

Proof: Necessity: Let (X, τ) be a $g\eta R_1$ space. Let $k \in X - g\eta cl(\{l\})$. Then $g\eta cl(\{k\}) \neq g\eta cl(\{l\})$, so k and l have disjoint $g\eta$ -open neighbourhoods.

Sufficiency: First to show that (X, τ) is $g\eta R_0$ space. Let G be a $g\eta$ -open set and $k \in G$. Suppose that $l \notin G$. Then, $g\eta cl(\{l\}) \cap G = \varphi$ and $k \notin g\eta cl(\{l\})$. There exists two $g\eta$ -open sets G_x and G_y such that $k \in G_x, l \in G_y$ and $G_x \cap G_y = \varphi$. Hence, $g\eta cl(\{k\}) \subseteq g\eta cl(\{G_x\})$ and $g\eta cl(\{k\}) \cap G_y \subseteq g\eta cl(\{G_x\}) \cap G_y = \varphi$. [For since G_y is a $g\eta$ -open set, $(X - G_y)$ is a $g\eta$ -closed set. So $g\eta cl(\{(X - G_y)\}) = (X - G_y)$. Also since $G_x \cap G_y = \varphi$ and $G_x \subseteq (X - G_y)$. So $g\eta cl(\{G_x\}) \subseteq g\eta cl(\{(X - G_y)\})$. Thus $g\eta cl(\{G_x\}) \subseteq (X - G_y)$]. Therefore, $l \notin g\eta cl(\{k\})$. Consequently, $g\eta cl(\{k\}) \subseteq G$ and (X, τ) is a $g\eta R_0$ space. Next to show that (X, τ) is a $g\eta R_1$ space. Suppose that

$g\eta cl(\{k\}) \neq g\eta cl(\{l\})$. Then, assume that there exists $m \in g\eta cl(\{k\})$ such that $m \notin g\eta cl(\{l\})$. There exists two $g\eta$ -open sets H_m and H_l such that $m \in H_m$, $l \in H_l$ and $H_m \cap H_l = \varphi$. Since $m \in g\eta cl(\{k\})$, $k \in H_m$. Since (K, β) is $g\eta R_0$ space, we obtain $g\eta cl(\{k\}) \subseteq H_m$, $g\eta cl(\{l\}) \subseteq H_l$ and $H_m \cap H_l = \varphi$. Therefore (X, τ) is $g\eta R_1$ space.