

CHAPTER-7

CHAPTER - 7

FINITE-TIME STABILITY OF MULTI-TERM IMPULSIVE NONLINEAR FRACTIONAL-ORDER SYSTEMS WITH MULTIPLE TIME-VARYING DELAYS

7.1 INTRODUCTION

This chapter deals with the problem of nonlinear multi-term fractional-order systems defined over the finite interval of time. Also, this problem having the existence of multiple time varying delays in the state variable and having the external disturbances. The results related to FTS of fractional-order impulsive systems have been reported in the literature [4, 55, 62, 66]. The FTS concept have been discussed for fractional-order system with the existence of time-varying delay with the help of Bellman-Gronwall inequality [43]. The generalized Gronwall inequality is one of the very successful method to discuss the FTS analysis. FTS results of some fractional-order systems has been analyzed by utilizing the generalized Gronwall inequality [33, 29, 30, 66, 75, 78, 89]. Motivated from the above literatures, our main aim is to study the FTS problem for the multi-term impulsive fractional systems with multiple time-varying delay by using the generalized Gronwall's inequality. The multi-term nonlinear impulsive fractional-order system with multiple time varying delay described by

$$\begin{cases} {}_0^C D_t^{\alpha_1} y(t) - \mathcal{A} {}_0^C D_t^{\alpha_2} y(t) = \mathcal{B}_0 y(t) + \sum_{i=1}^n \mathcal{B}_i y(t - \rho_i(t)) + f(t, y(t), y(t - \rho_1(t))), \\ y(t - \rho_2(t)), \dots, y(t - \rho_n(t)), w(t) + \mathcal{D}w(t), \quad t \in L', \\ \Delta y(t_k) = M_k(y(t_k^-)), \Delta y'(t_k) = N_k(y(t_k^-)), \quad k = 1, 2, 3, \dots, m, \\ y(t) = \phi_1(t), \quad y'(t) = \phi_2(t), \quad -\rho \leq t \leq 0, \end{cases} \quad (7.1.1)$$

where $\alpha_1 \in (1, 2]$, $\alpha_2 \in (0, 1]$. $y(t)$ is in \mathbb{R}^n which indicates the state vector. The disturbance term $w(t) \in \mathbb{R}^m$ satisfies that there exists $\lambda > 0$ such that $\|w(t)\| \leq \lambda$. ${}_0^C D_t^{\alpha_1}$ and ${}_0^C D_t^{\alpha_2}$ are the fractional derivatives with Caputo fractional-order α_1 and α_2 respectively. The constant matrices $\mathcal{A}, \mathcal{B}_i, i = 0, 1, \dots, n$ are the elements of $\mathbb{R}^{n \times n}$ and matrix \mathcal{D} is the element of $\mathbb{R}^{n \times m}$. $\rho_i(t), i = 1, 2, \dots, n$ are time varying delays with $0 \leq \rho_i(t) \leq \rho, \forall i = 1, 2, \dots, n$.

Here, L' is defined by $L = [0, T]$, $L' = L - \{t_1, \dots, t_m\}$ and

$$0 = t_0 < t_1 < t_2 < \dots < t_m = T < \infty.$$

Also, $f(\cdot) : L \times \mathbb{R}^n \times \mathbb{R}^n \cdots \times \mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{R}^n$ is a nonlinear function which satisfies

$$\begin{aligned} \|f(t, x, y, \dots, z, w)\| &\leq d(t)(\|x\| + \|y\| + \dots + \|z\| + \|w\|), \\ \forall (t, x, y, \dots, z, w) \in L \times \mathbb{R}^n \times \mathbb{R}^n \cdots \times \mathbb{R}^n \times \mathbb{R}^m. \end{aligned}$$

$\Delta y(t_k) = y(t_k^+) - y(t_k^-)$, where $y(t_k^+) = \lim_{\epsilon \rightarrow 0^+} y(t_k + \epsilon)$ and $y(t_k^-) = \lim_{\epsilon \rightarrow 0^-} y(t_k + \epsilon)$ and $\Delta y'(t_k)$ is similarly defined.

Definition 7.1.1. [50, 60] The system described by (7.1.1) is finite-time stable with respect to $\{t_0, L, \delta, \epsilon, \rho\}$, iff $\kappa < \delta$ implies $\|y(t)\| < \epsilon, \forall t \in L$. Here $\kappa = \max \{\|\phi_1(t)\|, \|\phi_2(t)\|\}$ and δ, ϵ are positive constants.

7.2 MAIN RESULTS

This section provides the condition for FTS of a solution of the system (7.1.1). For this, the following notations are introduced.

$$\kappa(t) = \sup_{\vartheta \in [0, t]} (n+1) \left(\sigma + d(\vartheta) \right) \text{ and } \zeta = \sup_{\vartheta \in [0, t]} (\|\mathcal{D}\| + d(\vartheta)).$$

Theorem 7.2.1. The system (7.1.1) is said to be finite-time stable, if

$$\begin{aligned} &\left\{ \delta \left(1 + t + \frac{\|\mathcal{A}\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} \right) + \frac{\zeta \lambda}{\Gamma(\alpha_1 + 1)} t^{\alpha_1} \right\} E_\gamma \left\{ r(t) \left(\Gamma(\alpha_1 - \alpha_2) t^{\alpha_1 - \alpha_2} \right. \right. \\ &\quad \left. \left. + \Gamma(\alpha_1) t^{\alpha_1} \right) \right\} + \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|) \|y(t_k)\| < \epsilon, \forall t \in L, \end{aligned} \tag{7.2.1}$$

holds, where $\gamma = \min \{\alpha_1, \alpha_1 - \alpha_2\}$.

Proof. The solution $y(t)$ of (7.1.1) becomes

$$\begin{aligned} y(t) &= y(0) + ty'(0) - \frac{\mathcal{A}y(0)t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{\mathcal{A}}{\Gamma(\alpha_1-\alpha_2)} \int_0^t (t-\vartheta)^{\alpha_1-\alpha_2-1} y(\vartheta) d\vartheta \\ &\quad + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t-\vartheta)^{\alpha_1-1} [\mathcal{B}_0 y(\vartheta) + \sum_{i=1}^n \mathcal{B}_i y(\vartheta - \rho_i(\vartheta)) + f(\vartheta, y(\vartheta)) + \mathcal{D}w(\vartheta)] d\vartheta \\ &\quad + \sum_{k=1}^m M_k y(t_k) + \sum_{k=1}^m N_k y(t_k). \end{aligned} \quad (7.2.2)$$

Applying $\|\cdot\|$ on each side of the equation (7.2.2),

$$\begin{aligned} \|y(t)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)} \int_0^t (t-\vartheta)^{\alpha_1-\alpha_2-1} \\ &\quad \|y(\vartheta)\| d\vartheta + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t-\vartheta)^{\alpha_1-1} \left\| \mathcal{B}_0 y(\vartheta) + \sum_{i=1}^n \mathcal{B}_i y(\vartheta - \rho_i(\vartheta)) \right. \\ &\quad \left. + f(\vartheta, y(\vartheta)), y(\vartheta - \rho_1(\vartheta)), y(\vartheta - \rho_2(\vartheta)), \dots, y(\vartheta - \rho_n(\vartheta)), w(\vartheta) \right\| d\vartheta \\ &\quad + \|\mathcal{D}w(\vartheta)\| d\vartheta + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\|. \end{aligned} \quad (7.2.3)$$

Now

$$\begin{aligned} \|\mathcal{B}_0 y(t) + \sum_{i=1}^n \mathcal{B}_i y(t - \rho_i(t)) + f(t, y(t), y(t - \rho_1(t)), y(t - \rho_2(t)), \dots, y(t - \rho_n(t)), \\ w(t)) + \mathcal{D}w(t)\| &\leq \|\mathcal{B}_0\| \|y(t)\| + \sum_{i=1}^n \|\mathcal{B}_i\| \|y(t - \rho_i(t))\| + \|f(t, y(t), y(t - \rho_1(t)), \\ &\quad y(t - \rho_2(t)), \dots, y(t - \rho_n(t)), w(t))\| + \|\mathcal{D}w(t)\|. \end{aligned} \quad (7.2.4)$$

Consider

$$\sigma_1 = \max_{1 \leq i \leq n} \sigma_{max}(\mathcal{B}_i), \quad \sigma = \max \{\sigma_{max}(\mathcal{B}_0), \sigma_1\}.$$

From this assumption,

$$\|\mathcal{B}_i\| \leq \sigma; \quad \forall i = 0, 1, 2, \dots, n. \quad (7.2.5)$$

Also from Lipschitz nonlinearity

$$\begin{aligned} \|f(t, y(t), y(t - \rho_1(t)), y(t - \rho_2(t)), \dots, y(t - \rho_n(t)), w(t))\| &\leq d(t)(\|y(t)\| \\ &\quad + \sum_{i=1}^n \|y(t - \rho_i(t))\| + \|w(t)\|). \end{aligned} \quad (7.2.6)$$

Substitute (7.2.5) and (7.2.6) in (7.2.4),

$$\begin{aligned} & \|\mathcal{B}_0 y(t) + \sum_{i=1}^n \mathcal{B}_i y(t - \rho_i(t)) + f(t, y(t), y(t - \rho_1(t)), y(t - \rho_2(t)), \dots, y(t - \rho_n(t)), \\ & \quad w(t)) + \mathcal{D}w(t)\| \leq \sigma \|y(t)\| + \sum_{i=1}^n \sigma \|y(t - \rho_i(t))\| + d(t)(\|y(t)\| \\ & \quad + \sum_{i=1}^n \|y(t - \rho_i(t))\| + \|w(t)\|) + \|\mathcal{D}\| \|w(t)\|. \end{aligned}$$

From inequality (7.2.3),

$$\begin{aligned} \|y(t)\| & \leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} \\ & \quad \|y(\vartheta)\| d\vartheta + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t - \vartheta)^{\alpha_1 - 1} \left\{ \sigma \|y(\vartheta)\| + \sum_{i=1}^n \sigma \|y(\vartheta - \rho_i(\vartheta))\| \right. \\ & \quad \left. + d(\vartheta) \left(\|y(\vartheta)\| + \sum_{i=1}^n \|y(\vartheta - \rho_i(\vartheta))\| + \|w(\vartheta)\| \right) + \|\mathcal{D}\| \|w(\vartheta)\| \right\} d\vartheta \\ & \quad + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\|. \end{aligned} \tag{7.2.7}$$

Now let

$$\begin{aligned} z(t) = \sup_{\eta \in [-\rho, t]} \|y(\eta)\|, \forall t \in L, \quad & \|y(\vartheta)\| \leq z(\vartheta), \|y(\vartheta - \rho_i(\vartheta))\| \leq z(\vartheta), \\ & \forall i = 1, 2, \dots, n, \vartheta \in [0, t]. \end{aligned}$$

Using the above condition, (7.2.7) becomes

$$\begin{aligned} \|y(t)\| & \leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} z(\vartheta) d\vartheta \\ & \quad + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t - \vartheta)^{\alpha_1 - 1} \left\{ \sigma(n+1)z(\vartheta) + d(\vartheta) \left((n+1)z(\vartheta) + \|w(\vartheta)\| \right) \right. \\ & \quad \left. + \|\mathcal{D}\| \|w(\vartheta)\| \right\} d\vartheta + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\|. \end{aligned} \tag{7.2.8}$$

From (7.2.8),

$$\begin{aligned} \|y(t)\| & \leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} z(\vartheta) d\vartheta \\ & \quad + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t - \vartheta)^{\alpha_1 - 1} \left\{ z(\vartheta)(n+1) (\sigma + d(\vartheta)) + (\|\mathcal{D}\| + d(\vartheta)) \right. \\ & \quad \left. \times \|w(\vartheta)\| \right\} d\vartheta + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\|. \end{aligned}$$

$$\begin{aligned}
\|y(t)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)} \int_0^t (t-\vartheta)^{\alpha_1-\alpha_2-1} z(\vartheta) d\vartheta \\
&\quad + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t-\vartheta)^{\alpha_1-1} (\kappa(t)z(\vartheta) + (\|\mathcal{D}\| + d(\vartheta))\|w(\vartheta)\|) d\vartheta \\
&\quad + \sum_{k=1}^m \|M_k\|\|y(t_k)\| + \sum_{k=1}^m \|N_k\|\|y(t_k)\|,
\end{aligned} \tag{7.2.9}$$

where $(n+1)(\sigma + d(\vartheta)) \leq \kappa(t)$.

$$\begin{aligned}
\|y(t)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1+1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)} \\
&\quad \times \int_0^t (t-\vartheta)^{\alpha_1-\alpha_2-1} z(\vartheta) d\vartheta + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^t (t-\vartheta)^{\alpha_1-1} z(\vartheta) d\vartheta \\
&\quad + \sum_{k=1}^m \|M_k\|\|y(t_k)\| + \sum_{k=1}^m \|N_k\|\|y(t_k)\| \\
&= \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1+1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)} \\
&\quad \times \int_0^t (\vartheta)^{\alpha_1-\alpha_2-1} z(t-\vartheta) d\vartheta + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^t (\vartheta)^{\alpha_1-1} z(t-\vartheta) d\vartheta \\
&\quad + \sum_{k=1}^m \|M_k\|\|y(t_k)\| + \sum_{k=1}^m \|N_k\|\|y(t_k)\|,
\end{aligned}$$

where $(\|\mathcal{D}\| + d(\vartheta)) \leq \zeta$. Note that $\forall \eta \in [0, t]$,

$$\begin{aligned}
\|y(\eta)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1+1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)} \\
&\quad \times \int_0^\eta (\vartheta)^{\alpha_1-\alpha_2-1} z(\eta-\vartheta) d\vartheta + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^\eta (\vartheta)^{\alpha_1-1} z(\eta-\vartheta) d\vartheta \\
&\quad + \sum_{k=1}^m \|M_k\|\|y(t_k)\| + \sum_{k=1}^m \|N_k\|\|y(t_k)\|.
\end{aligned}$$

Here $\int_0^t (\vartheta)^{\alpha_1-\alpha_2-1} z(t-\vartheta) d\vartheta$ and $\int_0^t (\vartheta)^{\alpha_1-1} z(t-\vartheta) d\vartheta$ are increasing for $t \geq 0$, due to the increasing of the non-negative function $z(t)$. So,

$$\begin{aligned}
\int_0^\eta (\vartheta)^{\alpha_1-\alpha_2-1} z(\eta-\vartheta) d\vartheta &\leq \int_0^t (\vartheta)^{\alpha_1-\alpha_2-1} z(t-\vartheta) d\vartheta, \\
\int_0^\eta (\vartheta)^{\alpha_1-1} z(\eta-\vartheta) d\vartheta &\leq \int_0^t (\vartheta)^{\alpha_1-1} z(t-\vartheta) d\vartheta.
\end{aligned}$$

Hence

$$\|y(\eta)\| \leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1+1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)}$$

$$\begin{aligned} & \times \int_0^t (\vartheta)^{\alpha_1 - \alpha_2 - 1} z(t - \vartheta) d\vartheta + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^t (\vartheta)^{\alpha_1 - 1} z(t - \vartheta) d\vartheta \\ & + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\|, \quad \forall \eta \in [0, t]. \end{aligned}$$

Now

$$\begin{aligned} z(t) &= \sup_{\eta \in [-\rho, t]} \|y(\eta)\| \leq \max \left\{ \sup_{\eta \in [-\rho, 0]} \|y(\eta)\|, \sup_{\eta \in [0, t]} \|y(\eta)\| \right\} \\ &\leq \max \left\{ \|\phi_1\|, \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\zeta \lambda}{\Gamma(\alpha_1 + 1)} t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \right. \\ &\quad \times \int_0^t (\vartheta)^{\alpha_1 - \alpha_2 - 1} z(t - \vartheta) d\vartheta + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^t (\vartheta)^{\alpha_1 - 1} z(t - \vartheta) d\vartheta \\ &\quad \left. + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\| \right\} \\ &= \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\zeta \lambda}{\Gamma(\alpha_1 + 1)} t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \\ &\quad \times \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} z(\vartheta) d\vartheta + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^t (t - \vartheta)^{\alpha_1 - 1} z(\vartheta) d\vartheta \\ &\quad + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\|. \end{aligned} \tag{7.2.10}$$

Introducing the nondecreasing function $v(t)$ such that

$$v(t) = \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\zeta \lambda}{\Gamma(\alpha_1 + 1)} t^{\alpha_1}.$$

Also let $r_1(t) = \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)}$ and $r_2(t) = \frac{\kappa(t)}{\Gamma(\alpha_1)}$.

Now (7.2.10) implies that

$$\begin{aligned} z(t) &\leq v(t) + r_1(t) \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} z(\vartheta) d\vartheta + r_2(t) \int_0^t (t - \vartheta)^{\alpha_1 - 1} z(\vartheta) d\vartheta \\ &\quad + \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|) \|y(t_k)\|. \end{aligned} \tag{7.2.11}$$

Hence applying the Lemma 1.6.4 to (7.2.11)

$$\begin{aligned} \|y(t)\| &\leq z(t) \leq v(t) E_\gamma \left\{ r(t) \left(\Gamma(\alpha_1 - \alpha_2) t^{\alpha_1 - \alpha_2} + \Gamma(\alpha_1) t^{\alpha_1} \right) \right\} \\ &\quad + \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|) \|y(t_k)\|, \end{aligned}$$

where $r(t) = r_1(t) + r_2(t)$ and $\gamma = \min\{\alpha_1, \alpha_1 - \alpha_2\}$. Now from the condition of FTS, the above inequality becomes,

$$\|y(t)\| \leq \left\{ \delta \left(1 + t + \frac{\|\mathcal{A}\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} \right) + \frac{\zeta \lambda}{\Gamma(\alpha_1 + 1)} t^{\alpha_1} \right\}$$

$$\times E_\gamma \{ r(t) (\Gamma(\alpha_1 - \alpha_2)t^{\alpha_1 - \alpha_2} + \Gamma(\alpha_1)t^{\alpha_1}) \} + \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|) \|y(t_k)\|.$$

Hence by (7.2.1),

$$\|y(t)\| < \epsilon, \forall t \in L.$$

This completes the proof. \square

Theorem 7.2.2. Suppose $\sum_{0 < t_k < t} (\|M_k\| + \|N_k\|) < 1$ holds. If

$$\frac{\{\delta(1 + t + \frac{\|\mathcal{A}\|t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)}) + \frac{\zeta\lambda}{\Gamma(\alpha_1 + 1)}t^{\alpha_1}\}}{(1 - \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|))} E_\gamma \{ r(t) (\Gamma(\alpha_1 - \alpha_2)t^{\alpha_1 - \alpha_2} + \Gamma(\alpha_1)t^{\alpha_1}) \} < \epsilon, \quad (7.2.12)$$

then (7.1.1) is said to be finite-time stable. Here $r(t)$ is the sum of $r_1(t)$ and $r_2(t)$.

Proof. Follow the same procedure as in Theorem 7.2.1,

$$\begin{aligned} \|y(t)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1 + 1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \\ &\quad \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} z(\vartheta) d\vartheta + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^t (t - \vartheta)^{\alpha_1 - 1} z(\vartheta) d\vartheta \\ &\quad + \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|) \|y(t_k)\|. \end{aligned} \quad (7.2.13)$$

From $\sum_{0 < t_k < t} (\|M_k\| + \|N_k\|) < 1$, (7.2.13) becomes

$$\begin{aligned} (1 - \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|)) \|y(t)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1 + 1)} \\ &\quad \times t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} z(\vartheta) d\vartheta \\ &\quad + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^t (t - \vartheta)^{\alpha_1 - 1} z(\vartheta) d\vartheta. \end{aligned} \quad (7.2.14)$$

Then (7.2.14) implies that

$$\begin{aligned} \|y(t)\| &\leq \frac{\|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1 + 1)}t^{\alpha_1}}{(1 - \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|))} \\ &\quad + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)(1 - \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|))} \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} z(\vartheta) d\vartheta \\ &\quad + \frac{\kappa(t)}{\Gamma(\alpha_1)(1 - \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|))} \int_0^t (t - \vartheta)^{\alpha_1 - 1} z(\vartheta) d\vartheta. \end{aligned} \quad (7.2.15)$$

Now follow the steps as in Theorem 7.2.1 and introducing the nondecreasing function $v(t)$ as

$$v(t) = \frac{\|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1+1)}t^{\alpha_1}}{(1 - \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|))}.$$

$$\text{Let } r_1(t) = \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)(1 - \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|))} \text{ and } r_2(t) = \frac{\kappa(t)}{\Gamma(\alpha_1)(1 - \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|))}.$$

Then (7.2.15) implies

$$\|y(t)\| \leq z(t) \leq v(t) + r_1(t) \int_0^t (t-\vartheta)^{\alpha_1-\alpha_2-1} z(\vartheta) d\vartheta + r_2(t) \int_0^t (t-\vartheta)^{\alpha_1-1} z(\vartheta) d\vartheta.$$

Hence now applying the Lemma 1.6.4,

$$\|y(t)\| \leq z(t) \leq v(t) E_\gamma \{ r(t) (\Gamma(\alpha_1 - \alpha_2) t^{\alpha_1 - \alpha_2} + \Gamma(\alpha_1) t^{\alpha_1}) \},$$

here $r(t) = r_1(t) + r_2(t)$ and $\gamma = \min\{\alpha_1, \alpha_1 - \alpha_2\}$. Now applying the condition for the FTS, the above inequality becomes

$$\begin{aligned} \|y(t)\| &\leq \frac{\delta \left(1 + t + \frac{\|\mathcal{A}\| t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)}\right) + \frac{\zeta\lambda}{\Gamma(\alpha_1+1)} t^{\alpha_1}}{(1 - \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|))} \\ &\quad \times E_\gamma \{ r(t) (\Gamma(\alpha_1 - \alpha_2) t^{\alpha_1 - \alpha_2} + \Gamma(\alpha_1) t^{\alpha_1}) \}. \end{aligned}$$

Then, from (7.2.12)

$$\|y(t)\| < \epsilon, \forall t \in L.$$

Hence the proof. \square

Corollary 7.2.1. *The linear fractional system described by*

$$\begin{cases} {}_0^C D_t^{\alpha_1} y(t) - \mathcal{A}_0^C D_t^{\alpha_2} y(t) = \mathcal{B}_0 y(t) + \sum_{i=1}^n \mathcal{B}_i y(t - \rho_i(t)) + \mathcal{D} w(t), & t \in L', \\ \Delta y(t_k) = M_k(y(t_k^-)), \Delta y'(t_k) = N_k(y(t_k^-)), & k = 1, 2, \dots, m, \\ y(t) = \phi_1(t), y'(t) = \phi_2(t), -\rho \leq t \leq 0, & \end{cases} \quad (7.2.16)$$

is finite-time stable for $\{L, \delta, \epsilon, \rho\}$ if

$$\frac{\{\delta \left(1 + t + \frac{\|\mathcal{A}\| t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)}\right) + \frac{d\lambda}{\Gamma(\alpha_1+1)} t^{\alpha_1}\}}{(1 - \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|))} E_\gamma \{ r(t) (\Gamma(\alpha_1 - \alpha_2) t^{\alpha_1 - \alpha_2} + \Gamma(\alpha_1) t^{\alpha_1}) \} < \epsilon, \quad (7.2.17)$$

holds, where $\|\mathcal{D}\| \leq d$, $r_1(t) = \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)(1 - \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|))}$ and $r_2(t) = \frac{\sigma(n+1)}{\Gamma(\alpha_1)(1 - \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|))}$.

Proof. The solution $y(t)$ of (7.2.16) becomes

$$\begin{aligned} y(t) &= y(0) + ty'(0) - \frac{\mathcal{A}y(0)t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\mathcal{A}}{\Gamma(\alpha_1 - \alpha_2)} \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} y(\vartheta) d\vartheta \\ &\quad + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t - \vartheta)^{\alpha_1 - 1} [\mathcal{B}_0 y(\vartheta) + \sum_{i=1}^n \mathcal{B}_i y(\vartheta - \rho_i(\vartheta)) + \mathcal{D}w(\vartheta)] d\vartheta \\ &\quad + \sum_{k=1}^m M_k y(t_k) + \sum_{k=1}^m N_k y(t_k). \end{aligned} \quad (7.2.18)$$

Applying $\|\cdot\|$ on each side of the equation (7.2.18),

$$\begin{aligned} \|y(t)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} \|y(\vartheta)\| d\vartheta \\ &\quad + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t - \vartheta)^{\alpha_1 - 1} \|\mathcal{B}_0 y(\vartheta) + \sum_{i=1}^n \mathcal{B}_i y(\vartheta - \rho_i(\vartheta)) + \mathcal{D}w(\vartheta)\| d\vartheta \\ &\quad + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\|. \end{aligned} \quad (7.2.19)$$

Now

$$\begin{aligned} \|\mathcal{B}_0 y(t) + \sum_{i=1}^n \mathcal{B}_i y(t - \rho_i(t)) + \mathcal{D}w(t)\| &\leq \|\mathcal{B}_0\| \|y(t)\| \\ &\quad + \sum_{i=1}^n \|\mathcal{B}_i\| \|y(t - \rho_i(t))\| + \|\mathcal{D}w(t)\|. \end{aligned} \quad (7.2.20)$$

Consider

$$\sigma_1 = \max_{1 \leq i \leq n} \sigma_{\max}(\mathcal{B}_i), \quad \sigma = \max \{\sigma_{\max}(\mathcal{B}_0), \sigma_1\}.$$

From the above assumption,

$$\|\mathcal{B}_i\| \leq \sigma; \quad \forall i = 0, 1, 2, \dots, n. \quad (7.2.21)$$

Substitute (7.2.21) in (7.2.20),

$$\|\mathcal{B}_0 y(t) + \sum_{i=1}^n \mathcal{B}_i y(t - \rho_i(t)) + \mathcal{D}w(t)\| \leq \sigma \|y(t)\| + \sum_{i=1}^n \sigma \|y(t - \rho_i(t))\| + \|\mathcal{D}\| \|w(t)\|.$$

From inequality (7.2.19),

$$\|y(t)\| \leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} \|y(\vartheta)\| d\vartheta$$

$$\begin{aligned}
& + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t-\vartheta)^{\alpha_1-1} \left\{ \sigma \|y(\vartheta)\| + \sum_{i=1}^n \sigma \|y(\vartheta - \rho_i(t))\| + \|\mathcal{D}\| \|w(\vartheta)\| \right\} d\vartheta \\
& + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\|.
\end{aligned} \tag{7.2.22}$$

Now let

$$\begin{aligned}
z(t) = \sup_{\eta \in [-\rho, t]} \|y(\eta)\|, \forall t \in L, \quad & \|y(\vartheta)\| \leq z(\vartheta), \|y(\vartheta - \rho_i(\vartheta))\| \leq z(\vartheta), \\
& \forall i = 1, 2, \dots, n, \vartheta \in [0, t].
\end{aligned}$$

Then (7.2.22) becomes

$$\begin{aligned}
\|y(t)\| \leq & \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \int_0^t (t-\vartheta)^{\alpha_1-\alpha_2-1} z(\vartheta) d\vartheta \\
& + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t-\vartheta)^{\alpha_1-1} \left\{ \sigma(n+1)z(\vartheta) + \|\mathcal{D}\| \|w(\vartheta)\| \right\} d\vartheta \\
& + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\|.
\end{aligned} \tag{7.2.23}$$

$$\begin{aligned}
\|y(t)\| \leq & \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{d\lambda}{\Gamma(\alpha_1 + 1)} t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \\
& \times \int_0^t (t-\vartheta)^{\alpha_1-\alpha_2-1} z(\vartheta) d\vartheta + \frac{\sigma(n+1)}{\Gamma(\alpha_1)} \int_0^t (t-\vartheta)^{\alpha_1-1} z(\vartheta) d\vartheta \\
& + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\| \\
= & \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{d\lambda}{\Gamma(\alpha_1 + 1)} t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \\
& \times \int_0^t (\vartheta)^{\alpha_1-\alpha_2-1} z(t-\vartheta) d\vartheta + \frac{\sigma(n+1)}{\Gamma(\alpha_1)} \int_0^t (\vartheta)^{\alpha_1-1} z(t-\vartheta) d\vartheta \\
& + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\|,
\end{aligned}$$

where $\|\mathcal{D}\| \leq d$. Note that $\forall \eta \in [0, t]$,

$$\begin{aligned}
\|y(\eta)\| \leq & \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{d\lambda}{\Gamma(\alpha_1 + 1)} t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \\
& \times \int_0^\eta (\vartheta)^{\alpha_1-\alpha_2-1} z(\eta-\vartheta) d\vartheta + \frac{\sigma(n+1)}{\Gamma(\alpha_1)} \int_0^\eta (\vartheta)^{\alpha_1-1} z(\eta-\vartheta) d\vartheta \\
& + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\|.
\end{aligned}$$

The integral terms in the above equation $\int_0^t (\vartheta)^{\alpha_1-\alpha_2-1} z(t-\vartheta) d\vartheta$ and $\int_0^t (\vartheta)^{\alpha_1-1} z(t-\vartheta) d\vartheta$ are increasing for $t \geq 0$, due to the increasing of the function $z(t)$. So,

$$\begin{aligned}\int_0^\eta (\vartheta)^{\alpha_1-\alpha_2-1} z(\eta-\vartheta) d\vartheta &\leq \int_0^t (\vartheta)^{\alpha_1-\alpha_2-1} z(t-\vartheta) d\vartheta, \\ \int_0^\eta (\vartheta)^{\alpha_1-1} z(\eta-\vartheta) d\vartheta &\leq \int_0^t (\vartheta)^{\alpha_1-1} z(t-\vartheta) d\vartheta.\end{aligned}$$

Hence

$$\begin{aligned}\|y(\eta)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{d\lambda}{\Gamma(\alpha_1+1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)} \\ &\quad \times \int_0^t (\vartheta)^{\alpha_1-\alpha_2-1} z(t-\vartheta) d\vartheta + \frac{\sigma(n+1)}{\Gamma(\alpha_1)} \int_0^t (\vartheta)^{\alpha_1-1} z(t-\vartheta) d\vartheta \\ &\quad + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\|, \quad \forall \eta \in [0, t].\end{aligned}$$

Now

$$\begin{aligned}z(t) &= \sup_{\eta \in [-\rho, t]} \|y(\eta)\| \leq \max \left\{ \sup_{\eta \in [-\rho, 0]} \|y(\eta)\|, \sup_{\eta \in [0, t]} \|y(\eta)\| \right\} \\ &\leq \max \left\{ \|\phi_1\|, \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{d\lambda}{\Gamma(\alpha_1+1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)} \right. \\ &\quad \times \int_0^t (\vartheta)^{\alpha_1-\alpha_2-1} z(t-\vartheta) d\vartheta + \frac{\sigma(n+1)}{\Gamma(\alpha_1)} \int_0^t (\vartheta)^{\alpha_1-1} z(t-\vartheta) d\vartheta \\ &\quad \left. + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\| \right\} \\ &= \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{d\lambda}{\Gamma(\alpha_1+1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)} \\ &\quad \times \int_0^t (t-\vartheta)^{\alpha_1-\alpha_2-1} z(\vartheta) d\vartheta + \frac{\sigma(n+1)}{\Gamma(\alpha_1)} \int_0^t (t-\vartheta)^{\alpha_1-1} z(\vartheta) d\vartheta \\ &\quad + \sum_{k=1}^m \|M_k\| \|y(t_k)\| + \sum_{k=1}^m \|N_k\| \|y(t_k)\|. \tag{7.2.24}\end{aligned}$$

Now introducing the nondecreasing function $v(t)$ such that

$$v(t) = \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{d\lambda}{\Gamma(\alpha_1+1)}t^{\alpha_1}.$$

Also let $r_1(t) = \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)}$ and $r_2(t) = \frac{\sigma(n+1)}{\Gamma(\alpha_1)}$.

Now (7.2.24) implies that

$$\begin{aligned} z(t) &\leq v(t) + r_1(t) \int_0^t (t-\vartheta)^{\alpha_1-\alpha_2-1} z(\vartheta) d\vartheta + r_2(t) \int_0^t (t-\vartheta)^{\alpha_1-1} z(\vartheta) d\vartheta \\ &\quad + \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|) \|y(t_k)\|. \end{aligned} \quad (7.2.25)$$

Now from Lemma 1.6.4,

$$\begin{aligned} \|y(t)\| &\leq z(t) \leq v(t) E_\gamma \{ r(t) (\Gamma(\alpha_1 - \alpha_2) t^{\alpha_1 - \alpha_2} + \Gamma(\alpha_1) t^{\alpha_1}) \} \\ &\quad + \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|) \|y(t_k)\|, \end{aligned}$$

where $r(t) = r_1(t) + r_2(t)$ and $\gamma = \min\{\alpha_1, \alpha_1 - \alpha_2\}$. Hence from the conditions of FTS,

$$\begin{aligned} \|y(t)\| &\leq \left\{ \delta \left(1 + t + \frac{\|\mathcal{A}\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} \right) + \frac{d\lambda}{\Gamma(\alpha_1 + 1)} t^{\alpha_1} \right\} \\ &\quad E_\gamma \{ r(t) (\Gamma(\alpha_1 - \alpha_2) t^{\alpha_1 - \alpha_2} + \Gamma(\alpha_1) t^{\alpha_1}) \} + \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|) \|y(t_k)\|. \end{aligned}$$

Hence by (7.2.17),

$$\|y(t)\| < \epsilon, \forall t \in L.$$

This completes the proof. \square

Corollary 7.2.2. *The system (7.1.1) with the absence of impulsive behavior described by*

$$\begin{cases} {}_0^C D_t^{\alpha_1} y(t) - \mathcal{A} {}_0^C D_t^{\alpha_2} y(t) = \mathcal{B}_0 y(t) + \sum_{i=1}^n \mathcal{B}_i y(t - \rho_i(t)) + f(t, y(t), y(t - \rho_1(t))), \\ y(t - \rho_2(t)), \dots, y(t - \rho_n(t)), w(t) + \mathcal{D}w(t), \quad t \in L, \\ y(t) = \phi_1(t), \quad y'(t) = \phi_2(t), \quad -\rho \leq t \leq 0, \end{cases} \quad (7.2.26)$$

is said to be finite-time stable for $\{L, \delta, \epsilon, \rho\}$, if

$$\begin{aligned} &\left\{ \delta \left(1 + t + \frac{\|\mathcal{A}\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} \right) + \frac{\zeta \lambda}{\Gamma(\alpha_1 + 1)} t^{\alpha_1} \right\} \\ &E_\gamma \{ r(t) (\Gamma(\alpha_1 - \alpha_2) t^{\alpha_1 - \alpha_2} + \Gamma(\alpha_1) t^{\alpha_1}) \} < \epsilon, \quad \forall t \in L, \end{aligned} \quad (7.2.27)$$

holds, where $\|\mathcal{D}\| \leq d$, $r_1(t) = \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)}$ and $r_2(t) = \frac{\kappa(t)}{\Gamma(\alpha_1)}$.

Proof. The solution $y(t)$ of (7.2.26) becomes

$$\begin{aligned} y(t) &= y(0) + ty'(0) - \frac{\mathcal{A}y(0)t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{\mathcal{A}}{\Gamma(\alpha_1-\alpha_2)} \int_0^t (t-\vartheta)^{\alpha_1-\alpha_2-1} y(\vartheta) d\vartheta \\ &\quad + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t-\vartheta)^{\alpha_1-1} [\mathcal{B}_0 y(\vartheta) + \sum_{i=1}^n \mathcal{B}_i y(\vartheta - \rho_i(\vartheta)) + f(\vartheta, y(\vartheta), \\ &\quad y(\vartheta - \rho_1(\vartheta)), y(\vartheta - \rho_2(\vartheta)), \dots, y(\vartheta - \rho_n(\vartheta)), w(\vartheta)) + \mathcal{D}w(\vartheta)] d\vartheta. \end{aligned} \quad (7.2.28)$$

Applying $\|\cdot\|$ on each side of the equation (7.2.28),

$$\begin{aligned} \|y(t)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)} \int_0^t (t-\vartheta)^{\alpha_1-\alpha_2-1} \|y(\vartheta)\| d\vartheta \\ &\quad + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t-\vartheta)^{\alpha_1-1} \left\| \mathcal{B}_0 y(\vartheta) + \sum_{i=1}^n \mathcal{B}_i y(\vartheta - \rho_i(\vartheta)) + f(\vartheta, y(\vartheta), \right. \\ &\quad \left. y(\vartheta - \rho_1(\vartheta)), y(\vartheta - \rho_2(\vartheta)), \dots, y(\vartheta - \rho_n(\vartheta)), w(\vartheta)) + \mathcal{D}w(\vartheta) \right\| d\vartheta. \end{aligned} \quad (7.2.29)$$

Now

$$\begin{aligned} \left\| \mathcal{B}_0 y(t) + \sum_{i=1}^n \mathcal{B}_i y(t - \rho_i(t)) + f(t, y(t), y(t - \rho_1(t)), y(t - \rho_2(t)), \dots, y(t - \rho_n(t)), \right. \\ \left. w(t)) + \mathcal{D}w(t) \right\| \leq \|\mathcal{B}_0\| \|y(t)\| + \sum_{i=1}^n \|\mathcal{B}_i\| \|y(t - \rho_i(t))\| + \|f(t, y(t), y(t - \rho_1(t)), \right. \\ \left. y(t - \rho_2(t)), \dots, y(t - \rho_n(t)), w(t))\| + \|\mathcal{D}w(t)\|. \end{aligned} \quad (7.2.30)$$

Consider

$$\sigma_1 = \max_{1 \leq i \leq n} \sigma_{max}(\mathcal{B}_i), \quad \sigma = \max \{\sigma_{max}(\mathcal{B}_0), \sigma_1\}.$$

From this assumption,

$$\|\mathcal{B}_i\| \leq \sigma; \quad \forall i = 0, 1, 2, \dots, n. \quad (7.2.31)$$

Also from Lipschitz nonlinearity

$$\begin{aligned} \|f(t, y(t), y(t - \rho_1(t)), y(t - \rho_2(t)), \dots, y(t - \rho_n(t)), w(t))\| &\leq d(t)(\|y(t)\| \\ &\quad + \sum_{i=1}^n \|y(t - \rho_i(t))\| + \|w(t)\|). \end{aligned} \quad (7.2.32)$$

Substitute (7.2.31) and (7.2.32) in (7.2.30),

$$\begin{aligned} \|\mathcal{B}_0 y(t) + \sum_{i=1}^n \mathcal{B}_i y(t - \rho_i(t)) + f(t, y(t), y(t - \rho_1(t)), y(t - \rho_2(t)), \dots, y(t - \rho_n(t)), \\ w(t)) + \mathcal{D}w(t)\| \leq \sigma \|y(t)\| + \sum_{i=1}^n \sigma \|y(t - \rho_i(t))\| + d(t)(\|y(t)\| \\ + \sum_{i=1}^n \|y(t - \rho_i(t))\| + \|w(t)\|) + \|\mathcal{D}\| \|w(t)\|. \end{aligned}$$

From inequality (7.2.29),

$$\begin{aligned} \|y(t)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} \|y(\vartheta)\| d\vartheta \\ &\quad + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t - \vartheta)^{\alpha_1 - 1} \left\{ \sigma \|y(\vartheta)\| + \sum_{i=1}^n \sigma \|y(\vartheta - \rho_i(t))\| + d(\vartheta)(\|y(\vartheta)\| \right. \\ &\quad \left. + \sum_{i=1}^n \|y(\vartheta - \rho_i(\vartheta))\| + \|w(\vartheta)\|) + \|\mathcal{D}\| \|w(\vartheta)\| \right\} d\vartheta. \end{aligned} \quad (7.2.33)$$

Now let

$$\begin{aligned} z(t) = \sup_{\eta \in [-\rho, t]} \|y(\eta)\|, \forall t \in L, \quad &\|y(\vartheta)\| \leq z(\vartheta), \|y(\vartheta - \rho_i(\vartheta))\| \leq z(\vartheta), \\ &\forall i = 1, 2, \dots, n, \quad \vartheta \in [0, t]. \end{aligned}$$

Then (7.2.33) becomes

$$\begin{aligned} \|y(t)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} \\ &\quad \times z(\vartheta) d\vartheta + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t - \vartheta)^{\alpha_1 - 1} \left\{ \sigma(n+1)z(\vartheta) + d(\vartheta) \right. \\ &\quad \left. ((n+1)z(\vartheta) + \|w(\vartheta)\|) + \|\mathcal{D}\| \|w(\vartheta)\| \right\} d\vartheta. \end{aligned} \quad (7.2.34)$$

From (7.2.34),

$$\begin{aligned} \|y(t)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} z(\vartheta) d\vartheta \\ &\quad + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t - \vartheta)^{\alpha_1 - 1} \left\{ z(\vartheta)(n+1)(\sigma + d(\vartheta)) + (\|\mathcal{D}\| + d(\vartheta)) \right. \\ &\quad \left. \times \|w(\vartheta)\| \right\} d\vartheta. \\ &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\| \|\phi_1\| t^{\alpha_1 - \alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \\ &\quad \times \int_0^t (t - \vartheta)^{\alpha_1 - \alpha_2 - 1} z(\vartheta) d\vartheta + \frac{1}{\Gamma(\alpha_1)} \int_0^t (t - \vartheta)^{\alpha_1 - 1} (\kappa(t)z(\vartheta) \end{aligned}$$

$$+ (\|\mathcal{D}\| + d(\vartheta)) \|w(\vartheta)\| \) d\vartheta, \quad (7.2.35)$$

where $(n+1)(\sigma + d(\vartheta)) \leq \kappa(t)$. Then

$$\begin{aligned} \|y(t)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1 + 1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \\ &\quad \times \int_0^t (t - \vartheta)^{\alpha_1-\alpha_2-1} z(\vartheta) d\vartheta + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^t (t - \vartheta)^{\alpha_1-1} z(\vartheta) d\vartheta \\ &= \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1 + 1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \\ &\quad \times \int_0^t (\vartheta)^{\alpha_1-\alpha_2-1} z(t - \vartheta) d\vartheta + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^t (\vartheta)^{\alpha_1-1} z(t - \vartheta) d\vartheta, \end{aligned}$$

where $(\|\mathcal{D}\| + d(\vartheta)) \leq \zeta$. Note that $\forall \eta \in [0, t]$,

$$\begin{aligned} \|y(\eta)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1 + 1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \\ &\quad \times \int_0^\eta (\vartheta)^{\alpha_1-\alpha_2-1} z(\eta - \vartheta) d\vartheta + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^\eta (\vartheta)^{\alpha_1-1} z(\eta - \vartheta) d\vartheta. \end{aligned}$$

The integral terms in the above equation $\int_0^t (\vartheta)^{\alpha_1-\alpha_2-1} z(t - \vartheta) d\vartheta$ and $\int_0^t (\vartheta)^{\alpha_1-1} z(t - \vartheta) d\vartheta$ are increasing with respect to $t \geq 0$, due to the increasing function $z(t)$. So,

$$\begin{aligned} \int_0^\eta (\vartheta)^{\alpha_1-\alpha_2-1} z(\eta - \vartheta) d\vartheta &\leq \int_0^t (\vartheta)^{\alpha_1-\alpha_2-1} z(t - \vartheta) d\vartheta, \\ \int_0^\eta (\vartheta)^{\alpha_1-1} z(\eta - \vartheta) d\vartheta &\leq \int_0^t (\vartheta)^{\alpha_1-1} z(t - \vartheta) d\vartheta. \end{aligned}$$

Hence,

$$\begin{aligned} \|y(\eta)\| &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1 + 1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \\ &\quad \times \int_0^t (\vartheta)^{\alpha_1-\alpha_2-1} z(t - \vartheta) d\vartheta + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^t (\vartheta)^{\alpha_1-1} z(t - \vartheta) d\vartheta, \quad \forall \eta \in [0, t]. \end{aligned}$$

Now

$$\begin{aligned} z(t) &= \sup_{\eta \in [-\rho, t]} \|y(\eta)\| \leq \max \left\{ \sup_{\eta \in [-\rho, 0]} \|y(\eta)\|, \sup_{\eta \in [0, t]} \|y(\eta)\| \right\} \\ &\leq \max \left\{ \|\phi_1\|, \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1 - \alpha_2 + 1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1 + 1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1 - \alpha_2)} \right. \\ &\quad \left. \times \int_0^t (\vartheta)^{\alpha_1-\alpha_2-1} z(t - \vartheta) d\vartheta + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^t (\vartheta)^{\alpha_1-1} z(t - \vartheta) d\vartheta \right\} \end{aligned}$$

$$\begin{aligned}
z(t) &\leq \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1+1)}t^{\alpha_1} + \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)} \\
&\quad \times \int_0^t (t-\vartheta)^{\alpha_1-\alpha_2-1} z(\vartheta) d\vartheta + \frac{\kappa(t)}{\Gamma(\alpha_1)} \int_0^t (t-\vartheta)^{\alpha_1-1} z(\vartheta) d\vartheta \\
&\quad + \sum_{k=1}^m \|M_k\| \|y(t_k)\|. \tag{7.2.36}
\end{aligned}$$

Introducing the nondecreasing function $v(t)$ such that

$$v(t) = \|\phi_1\| + t\|\phi_2\| + \frac{\|\mathcal{A}\|\|\phi_1\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} + \frac{\zeta\lambda}{\Gamma(\alpha_1+1)}t^{\alpha_1}.$$

Also let $r_1(t) = \frac{\|\mathcal{A}\|}{\Gamma(\alpha_1-\alpha_2)}$ and $r_2(t) = \frac{\kappa(t)}{\Gamma(\alpha_1)}$.

Now (7.2.36) implies that

$$\begin{aligned}
z(t) &\leq v(t) + r_1(t) \int_0^t (t-\vartheta)^{\alpha_1-\alpha_2-1} z(\vartheta) d\vartheta + r_2(t) \int_0^t (t-\vartheta)^{\alpha_1-1} z(\vartheta) d\vartheta. \tag{7.2.37}
\end{aligned}$$

Hence from Lemma 1.6.4,

$$\|y(t)\| \leq z(t) \leq v(t) E_\gamma \{r(t)(\Gamma(\alpha_1-\alpha_2)t^{\alpha_1-\alpha_2} + \Gamma(\alpha_1)t^{\alpha_1})\},$$

where $r(t) = r_1(t) + r_2(t)$ and $\gamma = \min\{\alpha_1, \alpha_1 - \alpha_2\}$. Now considering the conditions of FTS,

$$\begin{aligned}
\|y(t)\| &\leq \left\{ \delta \left(1 + t + \frac{\|\mathcal{A}\|t^{\alpha_1-\alpha_2}}{\Gamma(\alpha_1-\alpha_2+1)} \right) + \frac{\zeta\lambda}{\Gamma(\alpha_1+1)}t^{\alpha_1} \right\} \\
&\quad E_\gamma \{r(t)(\Gamma(\alpha_1-\alpha_2)t^{\alpha_1-\alpha_2} + \Gamma(\alpha_1)t^{\alpha_1})\}.
\end{aligned}$$

Hence by (7.2.27),

$$\|y(t)\| < \epsilon, \forall t \in L.$$

This completes the proof. \square

Corollary 7.2.3. When $\alpha_1 = 2$ and $\alpha_2 = 1$, the system (7.1.1) reduces to the second order integer system

$$\begin{cases} \frac{d^2y(t)}{dt^2} - \mathcal{A} \frac{dy(t)}{dt} = \mathcal{B}_0 y(t) + \sum_{i=1}^n \mathcal{B}_i y(t - \rho_i(t)) + f(t, y(t), y(t - \rho_1(t))), \\ y(t - \rho_2(t)), \dots, y(t - \rho_n(t)), w(t) + \mathcal{D}w(t), \quad t \in L', \\ \Delta y(t_k) = M_k(y(t_k^-)), \Delta y'(t_k) = N_k(y(t_k^-)), \quad k = 1, 2, 3, \dots, m, \\ y(t) = \phi_1(t), \quad y'(t) = \phi_2(t), \quad -\rho \leq t \leq 0, \end{cases} \tag{7.2.38}$$

is said to be finite-time stable, if

$$\{\delta(1+t+\|\mathcal{A}\|t) + \frac{\zeta\lambda}{2}t^2\}e^{r(t)(t+t^2)} + \sum_{0 < t_k < t} (\|M_k\| + \|N_k\|)\|y(t_k)\| < \epsilon, \quad \forall t \in L,$$

holds, where $r_1(t) = \|\mathcal{A}\|$ and $r_2(t) = \kappa(t)$.

7.3 NUMERICAL EXAMPLES

Example 7.3.1. Consider the system

$$\begin{cases} {}_0^C D_t^{1.25}y(t) - \mathcal{A} {}_0^C D_t^{0.75}y(t) = \mathcal{B}_0 y(t) + \sum_{i=1}^2 \mathcal{B}_i y(t - \rho_i(t)) \\ + f(t, y(t), y(t - \rho_1(t)), y(t - \rho_2(t)), w(t)) + \mathcal{D}w(t), \quad t \in L', \\ \Delta y(t_k) = \frac{1}{4}(y(t_k^-)), \Delta y'(t_k) = \frac{1}{4}(y(t_k^-)), \quad k = 1, 2, \dots, m, \\ y(t) = 0, \quad y'(t) = 0, \quad -0.1 \leq t \leq 0, \end{cases} \quad (7.3.1)$$

where

$$y(t) = \begin{bmatrix} y_1(t) \\ y_2(t) \end{bmatrix}, \quad \mathcal{A} = \begin{bmatrix} 0 & 0.1 \\ 0.2 & 0 \end{bmatrix}, \quad \mathcal{B}_0 = \begin{bmatrix} 0 & 0 \\ 1 & -1 \end{bmatrix}, \quad \mathcal{B}_1 = \begin{bmatrix} 0 & 1 \\ 0 & 2 \end{bmatrix}, \\ \mathcal{B}_2 = \begin{bmatrix} 0 & 0 \\ 0.3 & 0.4 \end{bmatrix}, \quad \mathcal{D} = [0.2 \quad 0], \quad w(t) = \begin{bmatrix} \cos(t) \\ 0 \end{bmatrix} \text{ and}$$

$f(t, y(t), y(t - \rho_1(t)), y(t - \rho_2(t)), w(t)) = \{0.1y_2(t - \rho_1(t)) \cos(y_2(t - \rho_2(t))) + 0.1y_2(t) \cos(y_1(t - \rho_1(t))y_2(t - \rho_2(t))) + 0.1y_1(t - \rho_2(t)) \sin(y_1(t - \rho_2(t))y_2(t - \rho_1(t)))\}$. Let $\rho_1(t) = 0.1 \sin t$, $\rho_2(t) = 0.1 \cos t$. From this, $d(t) = 0.1$, $\rho = 0.1$, $\lambda = 1$, $\sigma = 2.2361$, $\|\mathcal{A}\| = 0.2$, $\|\mathcal{B}_0\| = 1.4142$, $\|\mathcal{B}_1\| = 2.2361$, $\|\mathcal{B}_2\| = 0.5$, $\kappa(t) = 6.9083$ and $\zeta = 0.3$. This implies that for chosen $\{\delta = 0.1, \epsilon = 100, \rho = 0.1\}$ and from the FTS condition of Theorem 7.2.2,

$$\frac{\{0.1(1+t+\frac{0.2t^{0.5}}{\Gamma(1.5)}) + \frac{0.3}{\Gamma(2.25)}t^{1.25}\}}{(1-0.5)} E_{0.5} \{15.68697(\Gamma(0.5)t^{0.5} + \Gamma(1.25)t^{1.25})\} < 100.$$

Hence, the estimated time of FTS is $T \approx 0.2003$.

Example 7.3.2. Consider the system

$$\begin{cases} {}_0^C D_t^{1.25}y(t) - \mathcal{A} {}_0^C D_t^{0.75}y(t) = \mathcal{B}_0 y(t) + \sum_{i=1}^2 \mathcal{B}_i y(t - \rho_i(t)) + \mathcal{D}w(t), \quad t \in L', \\ \Delta y(t_k) = \frac{1}{4}(y(t_k^-)), \Delta y'(t_k) = \frac{1}{4}(y(t_k^-)), \quad k = 1, 2, \dots, m, \\ y(t) = 0, \quad y'(t) = 0, \quad -1 \leq t \leq 0. \end{cases}$$

Here

$$y(t) = \begin{bmatrix} y_1(t) \\ y_2(t) \end{bmatrix}, \quad \mathcal{A} = \begin{bmatrix} 0 & 1 \\ -2 & 0 \end{bmatrix}, \quad \mathcal{B}_0 = \begin{bmatrix} 0 & 0 \\ 3 & 4 \end{bmatrix}, \quad \mathcal{B}_1 = \begin{bmatrix} 0 & 1 \\ 2 & -1 \end{bmatrix}, \quad \mathcal{B}_2 = \begin{bmatrix} -1 & 0 \\ 1 & -1 \end{bmatrix},$$

$$\mathcal{D} = \begin{bmatrix} 1 & 0 \end{bmatrix}, w(t) = \begin{bmatrix} \sin t \\ \cos t \end{bmatrix}, \rho_1(t) = \sin t \text{ and } \rho_2(t) = \cos t.$$

From this, $\|\mathcal{A}\| = 2$, $\|\mathcal{B}_0\| = 5$, $\|\mathcal{B}_1\| = 2.2883$, $\|\mathcal{B}_2\| = 1.6180$, $\sigma = 5$, $\lambda = 1$ and $d = 1$. Hence for chosen $\{\delta = 0.1, \epsilon = 100, \rho = 1\}$ and from the FTS condition of Corollary 7.2.1,

$$\frac{\{\delta(1+t+\frac{2t^{0.5}}{\Gamma(1.5)}) + \frac{1}{\Gamma(2.25)}t^{1.25}\}}{0.5} E_{0.5} \{35.3547(\Gamma(0.5)t^{0.5} + \Gamma(1.25)t^{1.25})\} < 100.$$

Hence, the estimated time of FTS is $T \approx 0.0475$.

Example 7.3.3. Consider the system

$$\begin{cases} {}_0^C D_t^{1.25} y(t) - \mathcal{A} {}_0^C D_t^{0.75} y(t) = \mathcal{B}_0 y(t) + \mathcal{B}_1 y(t-\rho_1(t)) + f(t, y(t), y(t-\rho_1(t)), w(t)) + \mathcal{D} w(t), \\ y(t) = 0.01, \quad y'(t) = 0.02, \quad -0.2 \leq t \leq 0, \end{cases}$$

where

$$y(t) = \begin{bmatrix} y_1(t) \\ y_2(t) \\ y_3(t) \end{bmatrix}, \quad \mathcal{A} = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{bmatrix}, \quad \mathcal{B}_0 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad \mathcal{B}_1 = \begin{bmatrix} 0 & 2 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 0.5 \end{bmatrix},$$

$\mathcal{D} = \begin{bmatrix} 0.1 & 0.2 & 0 \end{bmatrix}$ and $w(t) = 1$, $f(t, y(t), y(t-\rho_1(t)), w(t)) = \sin y(t) + \cos y(t-\rho_1(t))$.

Let $\rho_1(t) = 0.1 \cos t$. From this, $d(t) = 1$, $\rho = 0.1$, $\lambda = 1$, $\sigma = 3.6431$, $\|\mathcal{A}\| = 3.3256$, $\|\mathcal{B}_0\| = 1$, $\|\mathcal{B}_1\| = 3.6431$, $\kappa(t) = 9.2862$ and $\zeta = 1.2$. This implies that for chosen $\{\delta = 0.1, \epsilon = 100, \rho = 0.1\}$ and from the FTS condition of Corollary 7.2.2,

$$\{0.1(1+t+\frac{3.3256t^{0.5}}{\Gamma(1.5)}) + \frac{1.2}{\Gamma(2.25)}t^{1.25}\} E_{0.5} \{12.1213(\Gamma(0.5)t^{0.5} + \Gamma(1.25)t^{1.25})\} < 100.$$

Hence, the estimated time is $T \approx 0.0121$.